

**OpreX**<sup>™</sup>Data Acquisition

SMARTDAC+
Data Acquisition & Control

Data Acquisition System GM

# SMART DE H

## Data Acquisition & Control

Your business environment is complex and rapidly changing.

You need smart and powerful systems that can adapt to your process.

**SMARTDAC+** is a fresh approach to data acquisition and control,

with smart and simple touch operation as a design priority.

Measure, display and record process data with greater

levels of clarity, intelligence and accessibility.

The **SMARTDAC+** concept started with the GX/GP,

an integrated I/O and recording system

with a familiar touch operator interface.

Building upon the **SMARTDAC+** product family is the highly adaptable, scalable and easy to operate GM data logger.

Now that's SMART.



## Precise, Reliable & Adaptable

Decades of Yokogawa's innovative measuring technology has resulted in a flexible data logger that offers both reliability and ease of use.

## **Scalability**

Up to 420 ch per system / Plug and lock modules

#### **Ease of Use**

Web-based configuration / Live Web-based data viewing

#### **Mobile Connectivity**

Bluetooth / Mobile Application

#### **Open Network**

Modbus, EtherNet/IP, SLMP, and OPC-UA server PROFINET communication (GX90NW)

#### Reliability

Secure data storage / High accuracy measurement

#### **Noise Tolerance**

Electromagnetic relay module









1 Data Acquisition System GM 2



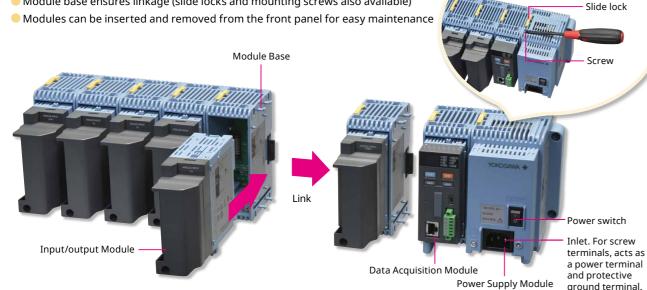
#### Ready for the future when you are

## **Smart Architecture**

#### Increase channels by adding additional block modules

YOKOGAWA proprietary block architecture [Patent technology]

- Expand one, or multiple module at a time
- Unique design houses modules in linked module bases
- Module base ensures linkage (slide locks and mounting screws also available)



#### Names of data acquisition module parts

7 segment LED (x2)-(Displays operation mode, system number, USER key (Executes specified actions)

SD memory card slot-

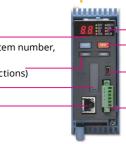
Comes standard with support for up to 100 ch

of measurement (single-unit configuration)

Up to 10 I/O modules can be linked to a single data

acquisition module (GM10)

Ethernet port A 10Base-T/100Base-TX port.



#### **Installs anywhere**

START/STOP key

For the desktop, DIN rails, or wall-mounting. No special attachments required.

Status display (Displays system status)

USB port (USB2.0 compliant port for

created communication programs)

Serial communications port

(Optional code, /C3)

(Starts/stops recording and computation)

hardware settings and the GA10, or customer

Desktop

Mounted on DIN rails

2 ways of linking:

slide lock and screw



\* There is a limit to the maximum number of connected modules depending on the module type. For details, please confirm the General Specifications.









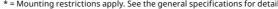
#### Select from a wide range of I/O modules

Select modules according to your application. Noise-resistant, magnetic relay types also available. All modules have removable terminal blocks for easy wiring. The same modules used in the SMARTDAC+ series.

Model					
GX90XA-10-U2		DC voltage, thermocouple, RTD, contact (solid state relay scanner type)	10	10	
GX90XA-10-L1		DC voltage, thermocouple, contact (Low withstand voltage solid state relay scanner type)	10	10	
GX90XA-10-T1*		DC voltage, thermocouple, contact (electromagnetic relay scanner type)	10	10	
GX90XA-10-C1	Analog input module	DC current (mA) (solid state relay scanner type)	10	10	
GX90XA-10-V1		DC voltage, contact (Solid state relay scanner type), High withstand voltage (600 V double insulation, 1000 VDC basic insulation)	10	10	
GX90XA-04-H0*		DC voltage, thermocouple, RTD, contact (individual A/D type)	4	4	
GX90XA-06-R1		4-wire RTD, 4-wire resistance(solid state relay scanner type)	6	6	
GX90YA*	Analog output module	Current output (Isolated between channels)	4	4	
GX90XD*	Digital input module	Remote control input or operation recording	16	16	
GX90YD*	Digital output module	Alarm output	6	6	
GX90WD*	Digital input/output module	Remote control input or operation recording/alarm output	14	DI:8/DO:6	
GX90XP	Pulse Input Module	Pulse signal data acquisition, integral count	10	10	
GX90UT*	PID control module	PID control (2 loop)	26	AI:2/AO:2 DI:8/DO:8	

0 0 0 0

0 0



10

Universal (-U2)

Electromagnetic relay (-T1)

High withstand voltage (-V1)

4-wire RTD/resistance (-R1)

Low withstand voltage relay (-L1) 10

Analog input module scan interval and measurement type

100ms

500ms

1s

100ms

100ms

SSR

SSR

Relay

SSR

SSR

#### Internal memory and max, I/O channels

	IIILEIIIat	illeliloi y allu	max. I/O Cita	illiets	
E tuma	Туре		Max. input/output channels		
Feature	GM10-1		Single-unit	0 to 100	
Universal		500MB	configuration		
Mid-price	GIVITO-1		Multi-unit configuration	0 to 100	
Noise-resistance			Corniguration		
mA only			Single-unit configuration	0 to 100	
High withstand	GM10-2	1.2GB	Corniguration		
voltage	GWTOZ	1,205	Multi-unit	0 to 420	
High speed			configuration	0 10 420	
measurement	* When an	alog input only			

#### **Actual values support high precision measurement**

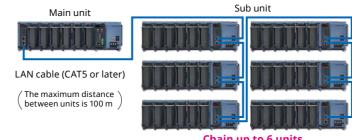
	Input type	Measuring accuracy*1 (typical value*2)
	20mV	$\pm$ (0.01% of rdg + 5 $\mu$ V)
DCV	60mV	$\pm$ (0.01% of rdg + 5 $\mu$ V)
	6V(1-5V)	$\pm$ (0.01% of rdg + 2 mV)
	R, S	± 1.1°C
	В	± 1.5℃
	K (-200.0 to 1370.0°C)	$\pm$ (0.01% of rdg +0.2°C for 0.0 to 1370.0°C; $\pm$ (0.15% of rdg +0.2°C) for -200.0 to 0.0°C
TC*3	K (-200.0 to 500.0°C)	$\pm$ 0.2°C for 0.0 to 500.0°C; $\pm$ (0.15% of rdg +0.2°C) for -200.0 to 0.0°C
	J	$\pm$ 0.2°C for 0.0 to 1100.0°C; $\pm$ (0.10% of rdg + 0.2°C) for -200.0 to 0.0°C
	T	$\pm$ 0.2°C for 0.0 to 400.0°C; $\pm$ (0.10% of rdg + 0.2°C) for -200.0 to 0.0°C
	N	$\pm$ (0.01% of rdg + 0.2°C) for 0.0 to 1300.0°C; $\pm$ (0.22% of rdg + 0.2°C) for -200.0 to 0.0°C
	Pt100 (-200.0 to 850.0°C)	$\pm$ (0.02% of rdg + 0.2°C)
RTD	Pt100 (high resolution) (-150.00 to 150.00°C)	$\pm (0.02\% \text{ of rdg} + 0.16^{\circ}\text{C})$

The measuring accuracies noted in the general specifications on page 15 have a margin of error that takes into account the product's components and the equipment used for adjustment and testing. However, the actual values calculated from the accuracy testing data upon shipment of the instrument from the factory are listed to the left.

- \*1 Applies to GX90XA-10-U2, A/D integration time 16.67ms or more, General operating conditions  $23 \pm 2^{\circ}$ C,  $55 \pm 10\%$  RH, supply voltage 90–132, 180–264V AC, power frequency within 50/60Hz ± 1%, warm-up of 30minutes or more, no vibrations or other hindrances to performance.
- \*2 For the measuring accuracy (guaranteed), see the module's general specifications (GS 04L53B01-01EN).
- \*3 These values do not include the reference junction compensation accuracy.

#### Support measurement of up to 420 ch (actual input) by expanding channels across multiple units (multi-unit configuration)

Expand up to 420 ch by using the GX90EX expansion module. (GM10-2) On the GM10-2 large capacity type, up to 1000 ch are available for recording when including MATH and communication channels. Connect units with LAN cables for dispersed installations.

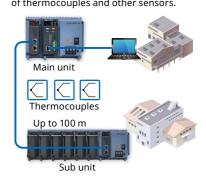


Chain up to 6 units

You connect directly with a LAN cable without connecting through a hub or repeater.

#### **Reduce wiring with** distributed installation

When the data logger is installed offsite (away from the DUT), you can place the sub unit at the site and monitor data without the need for long-distance wiring



<sup>\* =</sup> Mounting restrictions apply. See the general specifications for details.
\*1: Large memory model required if the total number of channels installed exceeds 100.

<sup>\*</sup> You can also connect a GX60 expansion unit



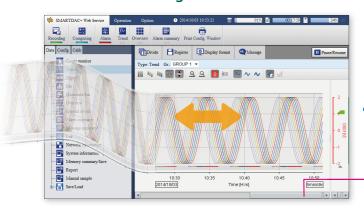
#### **Navigate with ease**

## **Smart User Interface**

#### Easy access from a Web browser

Through a Web browser you can monitor the GM in real time and change settings. You can easily build a seamless, low-cost remote monitoring system with no additional software.

#### Real time monitoring screen

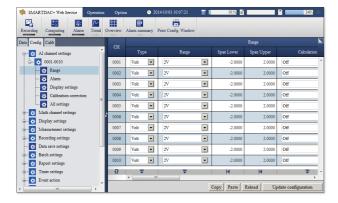






With the scroll bar, you can seamlessly scroll between past and current trends.

#### Enter settings online with a web browser

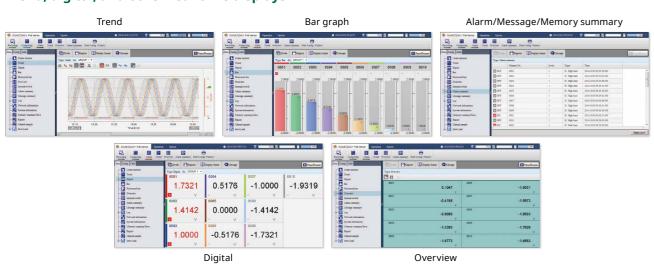


The setting screen lets you copy AI channel settings and other information to Excel for editing.

You can reimport the data into the setting screen after editing.

	A B	C	D	E	F	G	H	I	J	K
1	1 RTD	Pt1 00	0	150	Off	1	2	0	100	off
2	2 RTD	Pt1 00	0	150	Off	1	2	0	100	off
3	3 RTD	Pt1 00	0	150	Off	1	2	0	100	off
4	4 RTD	Pt1 00	0	150	Off	1	2	0	100	off
5	5 RTD	Pt1 00	0	150	Off	1	2	0	100	off
6	6 RTD	Pt1 00	0	150	Off	1	2	0	100	off
7	7 RTD	Pt1 00	0	150	Off	1	2	0	100	off
8	8 RTD	Pt1 00	0	150	Off	1	2	0	100	off
9	9 RTD	Pt1 00	0	150	Off	1	2	0	100	off
10	10 RTD	Pt1 00	0	150	Off	1	2	0	100	off
11										

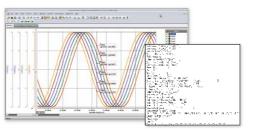
#### Trend, digital, and other real-time displays



#### Dedicated software (free download) is available for loading waveforms and GM settings

#### **Universal viewer**

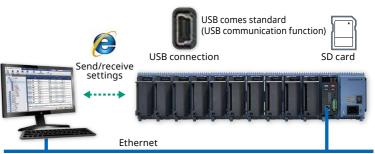
Data files saved on the GM can be viewed and printed. You can perform statistical computation over an area and export to ASCII, Excel, or other formats.



#### Data converted to an ASCII file

#### Offline setting software

Save settings or transfer them to the GM. Connections can also be made easily via USB or Bluetooth.



Load/save settings

#### Safe to use in a wide range of temperatures

With operating temperatures of -20°C-60°C, it supports a wide range of applications in varying installation environments.



Environmental testing

#### Monitoring and settings can also be done on a tablet

Supports Bluetooth (optional code /C8)

You can enter settings or monitor from a tablet without ever bringing a PC to the site.

Dedicated applications is available for free download. For more information, visit our website.

#### 







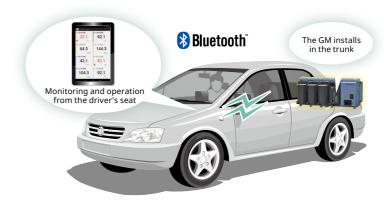
#### Powerful applications

#### **Bluetooth connection**

Simple to use for in-veheicle testing.

#### **USB** connection

Service staff can easily perform maintenance on the GM.





5 Data Acquisition System GM 6



#### Data analysis made simple and mobile

## **Smart Functionality**



#### Predictive monitoring with AI

#### **Equipment/Quality Easy Predictive Detection**

\* Creating predictive diagnostic models and profile waveforms requires the Equipment/Quality Predictive Detection tool (sold separately).

#### **Health Monitor Function**

By easily creating predictive detection models from past recorded OK/NG data and loading it into GM, you can detect prediction of abnormalities in manufacturing equipment and product quality degradation at an early stage. And because health scores—which show the degree of normal and abnormal data—consider correlations among multiple data to make determinations, they can capture prediction of abnormalities that are difficult for humans to detect.

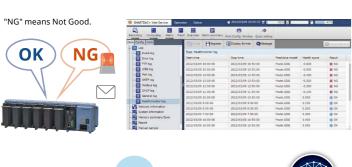
- Maximum number of channels: 20
- Shortest recording interval: 100 ms
- Target channels: I/O channel, math channel, and communication channel

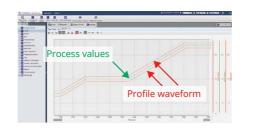
#### **Profile Function**

By creating a profile waveform from past recorded data and loading it into GM, this waveform can be used as a threshold for process values. Profile waveforms are useful in applications where process values change over time. Also, you can see the deviation from the reference waveform on the screen.

- Maximum number of channels: 20
- Shortest recording interval: 500 ms

\*/MC option required







**Equipment/Quality Predictive Detection tool** 

\* Certain restrictions apply with Equipment/Quality Easy Predictive Detection. See the general specifications for details.

#### High speed measurement (down to 1 ms)

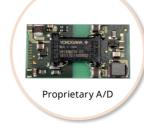
Yokogawa's proprietary A/D converter allows the high speed module to measure data points as fast 1ms.

- High speed (1 ms) measurement\*
- Proprietary A/D converter
- \* With 1ch per module. At 2 ms, 2 ch per module, and at 5 ms or more, all 4 ch per module.

#### Max. channels

Model	Scan interval				
GM10-1	1ch	5ch	10ch		
GM10-2	5ch	25ch	32ch		





GX90XA-04-H0 Analog input module (high speed AI)

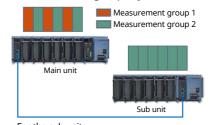
#### Dual interval measurement with two different scan intervals

Users have the ability to choose two different scan intervals on a single GM system. This allows users the flexibility to measure various types of inputs with two different scan intervals in a single system.

For example, this provides for efficient, simultaneous measurement of signals with slow fluctuations such as temperature, and fast-changing signals such as pressure and vibration. Modules can be assigned to measurement groups.

#### 2 measurement groups

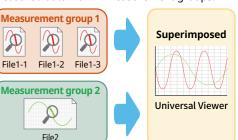
The figure above shows 2 measurement groups by color.



For the sub units,

#### Superimpose data on Universal Viewer

With Universal Viewer, you can superimpose measured data from 2 measurement groups.



#### **Application examples**

- Monitoring and recording of alarms when abnormal temperature or vibration are detected
- At 5 ms sampling, reliably detect abnormalities
- Dual interval multipoint



#### Measures LCD projector overheating

- Evaluates the rise in temperature of parts near the projector lamp, and the drop in temperature after powering OFF
- At 10 to 1 ms sampling, record steep temperature changes in detail



#### Car battery charge/discharge test

- Measures transient current during charging and discharging
- Sampling requirement: 1 ms



#### PID control function

#### **Control function**

Enables PID and program control

- PID control module 2-loops per module, up to 20 loops per system
- Setpoint program control function (/PG option) Up to 99 patterns







## PID control module

#### Remote operation and monitoring

The web application enables remote operation and monitoring from a browser.



#### **Application examples**

#### **Industrial furnace**

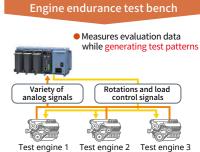
- Ideal for centralized control of multiple loops
- Modular structure makes for easy maintenance of individual loops

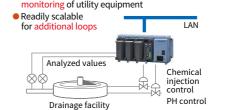


#### Utility equipment

\_\_\_\_\_

- Simplifies loop control and remote
- itoring of utility equipment





#### MATH (including reports), and event actions

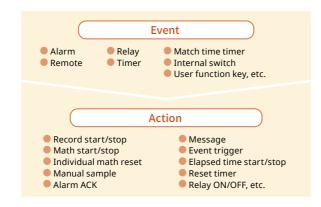
#### MATH function (/MT option)

Supports various kinds of math computation, including basic math and functions (square root, logarithms, F value, elapsed time, etc.). Elapsed time calculation allows you to measure the amount of time elapsed after a condition is met. Write formulas using variables for measured or computed data and save or display the results—this saves time and effort on post-processing. Create hourly, daily, monthly, and other reports with the Report function.



#### **Event actions**

Ability to assign actions tied to specific events during the operation of the data acquisition station.

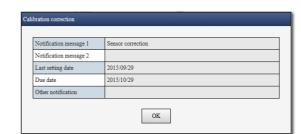


## Supports the aerospace industry's AMS2750/NADCAP and the automotive industry's IATF16949/CQI-9 for heat treatment applications

#### Calibration correction schedule control function (/AH option)

Schedule management for periodically executing calibration correction configuration and the like. You can set the input correction factor as a sensor correction factor and instrument correction factor. For AMS2750, we offer TUS software\* that can easily create TUS (Temperature Uniformity Survey) reports.

\* For information on TUS software, contact your Yokogawa representative.

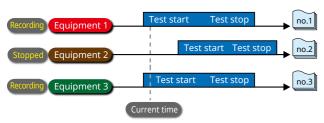


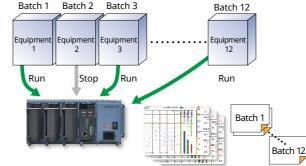
Input calibration is performed in the AI channel setting screen, and the calibration period settings are entered in the schedule management setting screen.

#### Record data in separate files per equipment set

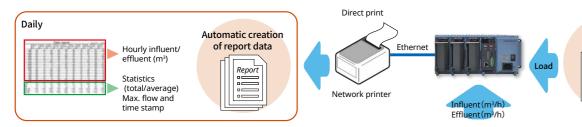
#### Multi-batch Function (/BT option)

Record pre-defined channel groups to separate data files with independent start and stop control. You can create up to 12 batches.





#### Report creation and network functions (/MT option)



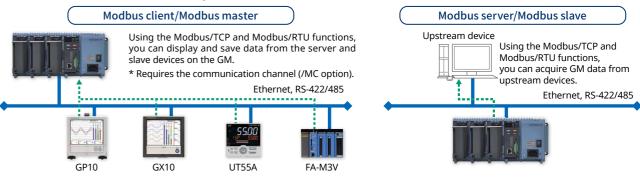
#### Provides a variety of convenient networking functions

# Networking

#### Modbus/TCP and Modbus/RTU communications

GM supports Modbus TCP/IP client and server modes for Ethernet communications and Modbus RTU master and slave modes for optional serial communications.

#### Modbus/TCP (Ethernet connection), Modbus/RTU (RS-422/485 connection)

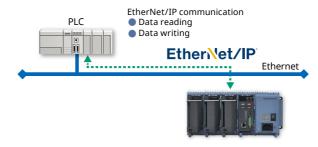


(You can connect up to 16 Modbus/TCP servers, or up to 32 servers with the GM10-2.) (You can connect up to 31 Modbus/RTU slaves.)

#### EtherNet/IP function (/E1 option)

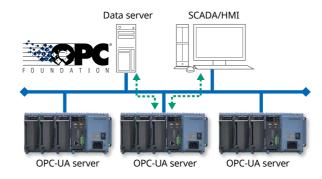
GM supports EtherNet/IP server functions. You can access GM from PLCs or other devices and load measurement/ MATH channels or write to communication input channels\* (GM10-1: up to 300 ch, GM10-2: up to 500 ch).

\* Communication channel function (/MC option) is required.



#### **OPC-UA Server** (/E3 option)

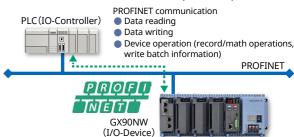
Data acquired by the GM can be accessed through Ethernet communication from a host system (OPCUA client). Writing from upstream systems to GM communication channels requires the communication channel function (/MC option).



#### PROFINET communication (GX90NW Network Module)

By using the GX90NW network module, you can connect the GM as a secondary I/O device via PROFINET. You can access the GM from the PLC or other I/O controller, read measurement/math channels, and write to communication channels\*. You can easily perform necessary operations for batch processes from the PLC.

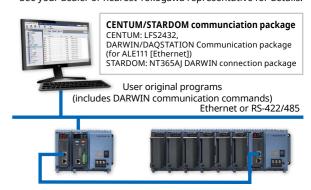
\* Communication channel function (/MC option) is required.



## Comes with communication functions that are compatible with the DARWIN data acquisition unit

The GM supports DARWIN communication commands. Use your current DARWIN communication programs as-is on the GM. It's easy to switch from an existing DARWIN unit.

\* See your dealer or nearest Yokogawa representative for details.



9 Data Acquisition System GM 10

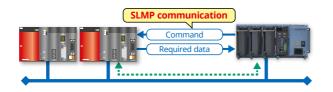
Record

templates

#### CC-Link family SLMP communication (/E4 option)

Protocol function that enables connection from a GM to Mitsubishi Electric PLCs without sequencer programs. The GM can run as the SLMP client to write to a GM measured data PLC, or PLC data to communication channels\*.

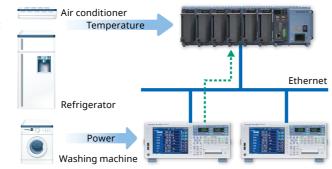
\* Requires the communication channel option (/MC option).



#### Data acquisition on power measuring instruments (/E2 and /MC options)

Acquire precise digital data on the GM by digital communication connectivity to a power measuring instrument (WT series power analyzers) and record it along with the GM's measured data. Since it records a device's power consumption, temperature, and other phenomena at the same time, the GM is ideal for performance evaluation testing.

Models that c an be connected Yokogawa Meters & Instruments Corp. WT1800/WT1800E (command type WT1800), WT500 WT300/WT300E (command mode WT300) Max. no. of connections 16



#### FTP-based file transfer

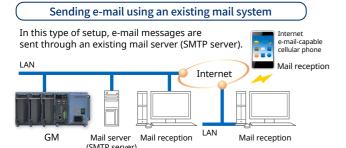
The FTP client/server functions allow you to easily share and manage data from a centralized file server



#### FTP client FTP server function Ethernet Internal memory/external storage: Data files Report files...etc. FTP server

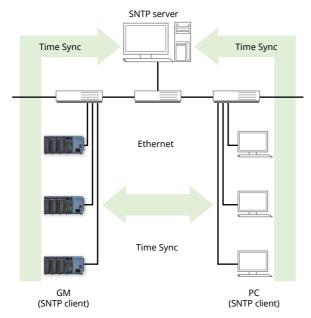
#### E-mail messaging function

The GM can send a variety of informative e-mail messages that include alarm notification reports, periodic instantaneous data values, scheduled report data and other information.



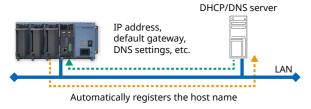
#### Time synchronization with network time servers

GM uses SNTP protocol in client mode to acquire time information from a network time-server. This function allows any number of GM units within a facility to have precisely synchronized time; all units will record data with coordinated date and time stamp information. In addition, GM can function as a server, providing time data to other SNTP client units on the network.



#### Automatic network setup (DHCP) function

Using Dynamic Host Configuration Protocol (DHCP), the GM can automatically acquire the settings it needs (IP address) for network communications from a DHCP server. This makes it easier than ever to install the unit on a plant network.



# ////

#### Rock-solid hardware and highly secure

# **Reliability and durability**

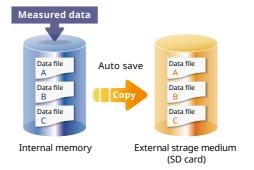
#### Be confident that recorded data is saved

Supports long-duration and multichannel recording. Measured data is always stored to internal memory, and data is transferred to external storage media at regular intervals. Redundancy can be achieved by sending data to a server with the FTP client function. Securely saves measured data even in the event of a sudden power loss.

Approximate sample time

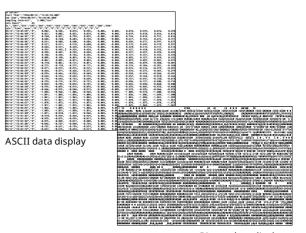
Number of recording channels	Total sample time
30	Approx. 71 days
100	Approx. 23 days
300	Approx. 7 days

With an internal memory of 1.2 GB and recording interval of 1 sec.



#### Select file formats according to your application

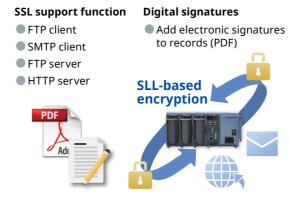
For increased security, measured data can be saved in binary format. This format is very difficult to decipher or modify in traditional text editors or other programs. To enable easy and direct opening of the data in text editors or spreadsheet programs, choose text format. This allows you to work with your measurement data without dedicated software.



Binary data display

#### **Security enhancements**

Safely sends and receives customer data.



SSL: An encryption protocol for data sent over TCP/IP networks.

#### **Key lock**

You can use settings to lock the GM10 operation keys in order to avoid accidental start/stop of measurement or computation.



#### 21 CFR Part 11 support (/AS option)

With the advanced security function, it supports US FDA 21 CFR Part 11 (regulations on electronic recording and electronic signatures) and the Japanese Ministry of Health, Labor, and Welfare's ER/ES guidelines. It also supports data integrity in accordance with ALCOA mentioned in PIC/S, WHO, MHRA and FDA guidance documents. It gives you access to a credentialbased login function, electronic signatures, audit trails, an anti-tampering function, an Active

Directorybased password management function, a sign-in function, and other security features.

FDA 21 CFR PART 11

#### Analog front end module

A proprietary A/D converter delivers high speed, high precision data acquisition. (High-speed AI,

PID Control module)



## **Specifications**

For detailed specs, see the general specifications (data acquisition module/power supply module/module base: GS 04L55B01-01EN, expansion unit/expansion modules:

GM10 Data Acquisition	n Module
No. of I/O channels:	GM10-1: 100 max.
	GM10-2: 500 max. (or 420 with AI only)
Measurement mode:	Normal, High speed <sup>*</sup> , Dual interval * Compatible modules: High-speed AI (GX90XA-04-H0)
Scan interval:	1/2/5/10/20/50/100/200/500ms/1/2/5s * Some intervals not available depending on system configuration and modules.
Internal memory (flash memory):	GM10-1: 500 MB GM10-2: 1.2 GB
External storage media:	SD memory card (SD/SDHC), up to 1–32 GB (1 GB incl.) Format: FAT32 or FAT16
Data types:	Event, display, alarm summary, manual sample, settings, and report (/MT option)
Data format:	Binary or text
Alarms:  Event actions:	Number: Max. 4 alarms per measurement channel Types: high limit, low limit, difference high limit, difference low limit, rate of change increase, rate of change decrease, delay high, delay low Specified actions can be performed when certain events occur.
Event actions.	Number: 50 Events: alarms, remote control input, etc.; Actions: record stop/start, alarm ACK, etc. Timers: 12 Match time timers: 12
Batch function:	Manage data by batch name. Enter text fields and batch comments in data files.
Calibration correction mode: Security functions:	Off, linearizer approximation, linearizer bias Key lock and login functions.
Insulation resistance:	Between RS-422/485/Ethernet terminals and internal circuitry:
Ethernet  Electrical/mechanical	20 MΩ or greater (at 500 VDC)  IEEE 802.3 compliant (Ethernet frame type: DIX specification)
specifications: Implemented protocols:	TCP, UDP, IP, ICMP, ARP, DHCP, HTTP, FTP, SMTP, SNTP, Modbus,
	dedicated protocol, SSL, DARWIN-compatible communication
USB communication Standards conformity: Connector format/no. of ports:	USB 2.0 compliant (recognized as a serial port by the PC) mini B/1
Implemented protocol:  RS-422/485 (/C3 option	Dedicated protocol
Media:	EIA RS-422/485 compliant
Implemented protocol:	Dedicated protocol, Modbus/RTU, or DARWIN compatible communicati
Bluetooth (/C8 option) Standards conformity:	Bluetooth® Ver 2.1+EDR compliant
Supported profiles:	SPP (serial port profile)
Communication range:	Approx. 10 m (depending on operating environment) (Class2)
Implemented protocol:	Dedicated protocol
EtherNet/IP communi Can join Ethernet/IP networks	
Max. connections:	20 (or 10 max. at TCP/IP level)
Supported protocols:	EIP/PCCC, EIP/native
Messaging: Objects:	Explict (UCMM Class 3) +I/O (Class 1) Assembly, PCCC, Data Table
WT communication (/I Models supported:	· · · · · · · · · · · · · · · · · · ·
Supported communication: Max. connected units:	Ethernet 16
Communication interval: Acquirable data types:	500 ms/1 s/2 s/5 s/10 s/20 s/30 s Voltage, current, power, power factor, phase, watt hours, harmonics,
Max. data assignments:	and others.
OPC-UA Server (/E3 op	
Communication:	ODC UA Comme
Type: Encoding:	OPC-UA Server UA Binary
Protocol:	OPC UA TCP
Maximum number of connections:	3 sessions
Profile:	Micro Embedded Device Server
Data acquisition:	Measurement channel, computation channel, communication channel value and alarm status
Data writing: Port number:	Measurement channel (DO channel only), communication channel 4840 (changeable: 1 to 65535)
Number of items:	300 max. (MonitoredItem/Session)
Fastest period:	100 ms
Number of connection destination servers:	(Mitsubishi PLC) (/E4 option) 16 max.
Read cycle: Communicable internal data:	100 ms, 200 ms, 500 ms, 1 s, 2 s, 5 s, 10 s, 20 s, 30 s, 1 min Special relay (SM), special register (SD), input (X), output (Y), internal relay (M), latch relay (L), annunciator (F), edge relay (V), link relay (B), data register (D), link register (W), timer contact (TS), timer coil (TC), current timer value (TN), integration timer contact (SS), integration timer coil (SC), current integration timer value (SN), counter contact (CS), counter coil (CC), current counter value (CN), special link relay (SB), special link register (SW), direct access input (DX direct access output (DY), index register (Z), file register (R, ZR),

● Program control (/PG option)<sup>\*</sup>
GX90UT PID control module is required. SMARTDAC + Hardware Configurator is required for program pattern setting.

Number of program pattern sets:	99 max. (Program patterns of up to 20 loops* can be stored in a single set.)
Number of segments:	99 segments/pattern
MATH (with Report fu	nction, /MT option)
No. of MATH channels:	GM10-1: 100, GM10-2: 200
MATH types:	Basic math, statistics, special operators, conditional statements, and others.
Communication chann	
No. of communication channels:	GM10-1: 300 (C001–C300) GM10-2: 500 (C001–C500)
Log scale (/LG option) Input types:	LOG input, pseudo log (input that supports pseudo log), LOG linear
Scalable range:	(linear input within the log decade) LOG input: 1.00E-15 to 1.00E+15 (max. 15 decades), [scale low limit] < [scale high limit] Pseudo log input/LOG linear: 1.00E-15 to 1.00E+15 (max. 15 decades), the
Multi batch Eunstion (	mantissa of the scale low and high limits are assumed to be the same.
Multi-batch Function ( Number of multi batches:	GM10-1: 6 max., GM10-2: 12 max.
Aerospace Heat Treats     Number of manageable	
schedules: Calibration correction mode: Number of set points:	Off, linearizer approximation, linearizer bias, correction coefficient 2 to 12
GM90PS Power Supply	
Rated supply voltage: Operating supply voltage:	100–240 VAC, 12-28 VDC (GM90PS-1N2W0) 90-132 VAC, 180-264 VAC, 10-32 VDC (GM90PS-1N2W0)
Power frequency (AC power supply):	50 Hz± 2%, 60 Hz± 2%
Insulation resistance: Withstand voltage:	Between power terminal and earth: $20~M\Omega$ or more (at $500~VDC$ ) Between power terminal and earth: $3000~VAC$ ( $50/60~Hz$ ), $1~minute$ $1000~VAC$ ( $50/60~Hz$ ) for $1~minute$ (GM90PS-1N2W0)
GX90XA Analog Input	Module
Universal input (-U2), low	withstand voltage relay (-L1), electromagnetic relay (-T1),
High-speed universal (-Ho Inputs:	D), 4-wire RTD/resistance (-R1), High withstand voltage (-V1) Universal / Low withstand voltage relay / Electromagnetic relay / High withstand voltage: 10, High-speed universal: 4,4-wire RTD/resistance: 6
Input types:	Universal, High-speed universal: DC voltage, standard signal, thermocouple, RTD, DI (voltage) Low withstand voltage relay, electromagnetic relay, High withstand voltage: DC voltage, standard signal, thermocouple, DI (voltage, contact)
Integral time:	4-wire RTD/resistance: 4-wire RTD, 4-wire resistance Universal, High withstand voltage: 1.67 ms/16.7 ms/20 ms/36.7 ms/100 ms Low withstand voltage relay, electromagnetic relay:
Innut calculation	16.7 ms/20 ms/36.7 ms/100 ms
Input calculation: Input range/accuracy:	Linear scaling, square root, differential calculations  Refer to the Measurement range and accuracy table.
Input resistance:	10 M $\Omega$ or more for thermocouple/DC voltage (1 V range or lower)
Input external resistance:	Approx. 1 M $\Omega$ for DC voltage (2 V range or higher)/standard signal 2 k $\Omega$ or lower for thermocouple/DC voltage
Effect of signal source resistance:	$\pm$ 10 $\mu$ V/1 $k\Omega$ or lower for thermocouple/DC voltage (1 V range or lower) $\pm$ 0.15%/1 $k\Omega$ or lower for DC voltage (2 V range or higher)/standard signal
Allowable wiring resistance:	Max. 10 $\Omega$ /1 wire or less (lead resistance between 3 wires is equal) for RTD input
Effect of wiring resistance:	$\pm$ 0.1°C/10 $\Omega$ (lead resistance between 3 wires is equal) for RTD input
Reference junction compensation accuracy:	Measurement of 0°C or higher, input terminal temp. balanced Type K, E, J, T, N, XK GOST: $\pm$ 0.5°C (23°C $\pm$ 2°C, $\pm$ 0.7°C (0 to 50°C), $\pm$ 1.0°C (-20 to 60°C) Type R, S, W, L, U, W97Re3-W75Re25, platinel 2, NiNiMo, WWRe26, N(AWG14): $\pm$ 1.0°C (23°C $\pm$ 2°C), $\pm$ 1.4°C (0 to 50°C), $\pm$ 2.0 (-20 to 60°C) Type KpvsAu7Fe: $\pm$ 1.0 K (23°C $\pm$ 2°C), $\pm$ 1.4 K (0 to 50°C).
	± 2.0 K (-20 to 60°C)  Type B, PR20-40: RJC fixed at 0°C  * Parentheses () = ambient temperature.
Allowable input voltage:	± 60V DC for DC voltage (2 V range or higher)/standard signal ± 10 V DC for other conditions.
Noise rejection ratio:	Normal mode: 50/60 Hz no rejection (integral time 1.67 ms), 40 dB or more (integral time 16.67 ms or more) Common mode: 80 dB or more (integral time 1.67 ms),
	120 dB or more (integral time 16.67 ms or more)
Max. common mode voltage:	30 VACrms (50/60Hz), or 60 VDC (however, max. common mode noise voltage of measurement input is 250 VACrms) High-speed universal: 300V ACrms (50/60Hz) High withstand voltage: 600 VACrms (50/60Hz) or 600 VDC double
	insulation, 1000 VDC basic insulation
Max. voltage between measurement input channels:	Universal, electromagnetic relay, 4-wire RTD/resistance, High withstand voltage: 30 VACrms (50/60Hz), or 60 VDC (however, max. common mode noise voltage between measurement input channels is 250 VACrms) Low withstand voltage relay: 30 VACrms (50/60Hz), or 60 VDC (however, max. common mode noise voltage between measurement input
	channels is 60 VACrms) High-speed universal: 300V ACrms (50/60Hz)
Effects of ambient temperature:	Applies when integral time is 16.67 ms or higher, $\pm$ (0.05% of rdg + 0.05% of range) or less fluctuation per 10°C change Note, KpvsAu7Fe, PR20-40: $\pm$ (0.05% of rdg + 0.1% of range) or less Cu10 $\Omega$ system: $\pm$ (0.2% of range + 0.1°C) or less
	Excluding guaranteed reference junction accuracy
Insulation resistance:	Between input terminals and internal circuitry: 20 $M\Omega$ or greater (at 500 VDC)
	(00.000 100)

(at 500 VDC)
Universal, electromagnetic relay, 4-wire RTD/resistance:
Between input terminals and internal circuitry: 3000 VAC, 1 minute
Between analog input channels: 1000 VAC, 1 minute (excluding b terminal
of universal input type)
Low withstand voltage relay:
Between input terminals and internal circuitry: 1500 VAC, 1 minute
Between analog input channels: 400 VAC, 1 minute
High-speed universal:
Between input terminals and internal circuitry: 3000 V AC, 1 minute
Between analog input channels: 3000 V AC, 1 minute
High withstand voltage:
Between input terminals and internal circuitry: 3700 V AC, 1 minute
Between analog input channels: 1000 V AC, 1 minute

DC current (mA) input (-C	
Inputs:	10  DC current (20 mA) ctandard current cional (4, 20 mA)
Input types:	DC current (20 mA), standard current signal (4–20 mA)
Integral time: Input calculation:	1.67 ms/16.7 ms/20 ms/36.7 ms/100 ms Linear scaling, square root, differential calculations
Input range:	Refer to the Measurement range and accuracy tables.
Input resistance:	250 Ω
Allowable input voltage:	± 10 VDC
Allowable input current:	24 mA *50/60 Hz, peak value including the signal portion
Noise rejection ratio:	Normal mode: 50/60 Hz no rejection (integral time 1.67 ms), 40 dB or more (integral time 16.67 ms or more) Common mode: 80 db or more (integral time 1.67 ms),
Max. common mode voltage:	120 dB or more (integral time 16.67 ms or more) 30 VACrms (50/60Hz) or 60 VDC (however, max. common mode noise voltage of measurement input is 250 VACrms)
Max. voltage between measurement input channels:	30 VACrms (50/60Hz) or 60 VDC (however, max. common mode noise voltage between measurement
Effects of ambient	input channels is 250 VACrms) Applies when integral time is 16.67 ms or more,
temperature:	±(0.075% of rdg + 0.05% of range) or less fluctuation per 10°C change
Insulation resistance:	Between input terminals and internal circuitry:
Withstand voltage:	20 MΩ or greater (at 500 VDC)  Between input terminals and internal circuitry: 1500 VAC, 1 minute
GX90XD Digital Input	Between analog input channels: 1000 VAC, 1 minute Module
Inputs: Input format:	16 Open collector or non-voltage contact
Range types	DI, pulse (250Hz (The chattering filter: OFF), 125Hz (The chattering filter: ON), min.
ON/OFF detection:	pulse width: 2 ms, requires the MATH (optional code /MT)).  Open collector: Voltage of 0.5 VDC or less when ON, leakage current of 0.5
	mA or less when OFF Non-voltage contact: Contact resistance of 200 $\Omega$ or less when ON, 50
	$k\Omega$ or more when OFF
Input calculation:	Linear scaling, differential calculations
Contact rating:	12 VDC, 20 mA or more
Input resistance: No. of common:	Approx. 1 kΩ 2 (1 common per 8 channels)
Allowable input voltage:	2 (1 common per 8 channels) 10 V
Insulation resistance:	Between input terminals and internal circuitry: 20 $M\Omega$ or greater
Withstand voltage:	(at 500 VDC)  Between input terminals and internal circuitry: 1500 VAC, 1 minute
GX90YD Digital Output	: Module
Outputs:	6
Output format:	Relay contact (c contact)
Rated load voltage:	30 VDC or 250 VAC or less
Max. load current:	3 A (DC)/3 A (AC), resistive load, each
Min. load voltage/current:	5 VDC/10 mA
No. of common:	6 (all outputs independent)
Insulation resistance:	Between output terminals and internal circuitry: 20 MΩ or greater (at 500 VDC)
Withstand voltage:	Between output terminals and internal circuitry: 3000 VAC, 1 minute
GX90WD Digital Input/	output Module
GX90WD Digital Input/ Digital input (DI) section	
Digital input (DI) section Inputs:	on 8
Digital input (DI) section	on 8 Open collector or non-voltage contact DI, pulse (250Hz (The chattering filter: OFF), 125Hz (The chattering filter:
Digital input (DI) section Inputs: Input format:	On 8 Open collector or non-voltage contact DI, pulse (250Hz (The chattering filter: OFF), 125Hz (The chattering filter: ON), min. pulse width: 2 ms, requires the MATH (optional code /MT)). Open collector: Voltage of 0.5 VDC or less when ON, leakage current of 0.5 mA or less when OFF Non-voltage contact: Contact resistance of 200 Ω or less when ON, 50
Digital input (DI) section Inputs: Input format: Range types:	On 8 Open collector or non-voltage contact DI, pulse (250Hz (The chattering filter: OFF), 125Hz (The chattering filter: ON), min. pulse width: 2 ms, requires the MATH (optional code /MT)). Open collector: Voltage of 0.5 VDC or less when ON, leakage current of 0.5 mA or less when OFF
Digital input (DI) section Inputs: Input format: Range types: ON/OFF detection: Input calculation:	One 8 Open collector or non-voltage contact DI, pulse (250Hz (The chattering filter: OFF), 125Hz (The chattering filter: ON), min. pulse width: 2 ms, requires the MATH (optional code /MT)). Open collector: Voltage of 0.5 VDC or less when ON, leakage current of 0.5 mA or less when OFF Non-voltage contact: Contact resistance of 200 $\Omega$ or less when ON, 50 k $\Omega$ or more when OFF Linear scaling, differential calculations
Digital input (DI) section Inputs: Input format: Range types: ON/OFF detection: Input calculation: Contact rating:	One 8 Open collector or non-voltage contact DI, pulse (250Hz (The chattering filter: OFF), 125Hz (The chattering filter: ON), min. pulse width: 2 ms, requires the MATH (optional code /MT)). Open collector: Voltage of 0.5 VDC or less when ON, leakage current of 0.5 mA or less when OFF Non-voltage contact: Contact resistance of 200 $\Omega$ or less when ON, 50 $k\Omega$ or more when OFF Linear scaling, differential calculations 12 VDC, 20 mA or more
Digital input (DI) section Inputs: Input format: Range types: ON/OFF detection:  Input calculation: Contact rating: Input resistance:	One 8 Open collector or non-voltage contact DJ, pulse (250Hz (The chattering filter: OFF), 125Hz (The chattering filter: ON), min. pulse width: 2 ms, requires the MATH (optional code /MT)). Open collector: Voltage of 0.5 VDC or less when ON, leakage current of 0.5 mA or less when OFF Non-voltage contact: Contact resistance of 200 $\Omega$ or less when ON, 50 k $\Omega$ or more when OFF Linear scaling, differential calculations 12 VDC, 20 mA or more Approx. 2.4 k $\Omega$
Digital input (DI) section Inputs: Input format: Range types: ON/OFF detection:  Input calculation: Contact rating: Input resistance: No. of common:	Open collector or non-voltage contact DI, pulse (250Hz (The chattering filter: OFF), 125Hz (The chattering filter: ON), min. pulse width: 2 ms, requires the MATH (optional code /MT)). Open collector: Voltage of 0.5 VDC or less when ON, leakage current of 0.5 mA or less when OFF Non-voltage contact: Contact resistance of 200 $\Omega$ or less when ON, 50 k $\Omega$ or more when OFF Linear scaling, differential calculations 12 VDC, 20 mA or more Approx. 2.4 k $\Omega$ 1 (1 common per 8 channels)
Digital input (DI) section Inputs: Input format: Range types: ON/OFF detection:  Input calculation: Contact rating: Input resistance:	One 8 Open collector or non-voltage contact DJ, pulse (250Hz (The chattering filter: OFF), 125Hz (The chattering filter: ON), min. pulse width: 2 ms, requires the MATH (optional code /MT)). Open collector: Voltage of 0.5 VDC or less when ON, leakage current of 0.5 mA or less when OFF Non-voltage contact: Contact resistance of 200 $\Omega$ or less when ON, 50 k $\Omega$ or more when OFF Linear scaling, differential calculations 12 VDC, 20 mA or more Approx. 2.4 k $\Omega$
Digital input (DI) section Inputs: Input format: Range types: ON/OFF detection:  Input calculation: Contact rating: Input resistance: No. of common: Allowable input voltage:	One 8 Open collector or non-voltage contact DI, pulse (250Hz (The chattering filter: OFF), 125Hz (The chattering filter: ON), min. pulse width: 2 ms, requires the MATH (optional code /MT)). Open collector: Voltage of 0.5 VDC or less when ON, leakage current of 0.5 mA or less when OFF Non-voltage contact: Contact resistance of 200 $\Omega$ or less when ON, 50 k $\Omega$ or more when OFF Linear scaling, differential calculations 12 VDC, 20 mA or more Approx. 2.4 k $\Omega$ 1 (1 common per 8 channels) 10 V Between input terminals and internal circuitry: 20 M $\Omega$ or greater
Digital input (DI) section Inputs: Input format: Range types: ON/OFF detection:  Input calculation: Contact rating: Input resistance: No. of common: Allowable input voltage: Insulation resistance: Withstand voltage:      Digital output (DO) section.	Open collector or non-voltage contact DI, pulse (250Hz (The chattering filter: OFF), 125Hz (The chattering filter: ON), min. pulse width: 2 ms, requires the MATH (optional code /MT)). Open collector: Voltage of 0.5 VDC or less when ON, leakage current of 0.5 mA or less when OFF Non-voltage contact: Contact resistance of 200 $\Omega$ or less when ON, 50 k $\Omega$ or more when OFF Linear scaling, differential calculations 12 VDC, 20 mA or more Approx. 2.4 k $\Omega$ 1 (1 common per 8 channels) 10 V Between input terminals and internal circuitry: 20 M $\Omega$ or greater (at 500 VDC) Between input terminals and internal circuitry: 1500 VAC, 1 minute cottion
Digital input (DI) section Inputs: Input format: Range types: ON/OFF detection:  Input calculation: Contact rating: Input resistance: No. of common: Allowable input voltage: Insulation resistance: Withstand voltage:      Digital output (DO) secont puts: Outputs:	One allowed terminals and internal circuitry: $20  \text{M}\Omega$ or greater (at $500  \text{VDC}$ ).
Digital input (DI) section Inputs: Input format: Range types: ON/OFF detection:  Input calculation: Contact rating: Input resistance: No. of common: Allowable input voltage: Insulation resistance: Withstand voltage:      Digital output (DO) section.	Open collector or non-voltage contact DI, pulse (250Hz (The chattering filter: OFF), 125Hz (The chattering filter: ON), min. pulse width: 2 ms, requires the MATH (optional code /MT)). Open collector: Voltage of 0.5 VDC or less when ON, leakage current of 0.5 mA or less when OFF Non-voltage contact: Contact resistance of 200 $\Omega$ or less when ON, 50 $k\Omega$ or more when OFF Linear scaling, differential calculations 12 VDC, 20 mA or more Approx. 2.4 $k\Omega$ 1 (1 common per 8 channels) 10 V Between input terminals and internal circuitry: 20 M $\Omega$ or greater (at 500 VDC) Between input terminals and internal circuitry: 1500 VAC, 1 minute ction 6 Relay contact (c contact) 150 VAC or less when connected to the main circuit (first-order power supply)
Digital input (DI) section Inputs: Inputs: Input format: Range types: ON/OFF detection:  Input calculation: Contact rating: Input resistance: No. of common: Allowable input voltage: Insulation resistance: Withstand voltage:     Digital output (DO) secontputs: Outputs: Outputs: Outputs: Output format:	Open collector or non-voltage contact DI, pulse (250Hz (The chattering filter: OFF), 125Hz (The chattering filter: ON), min. pulse width: 2 ms, requires the MATH (optional code /MT)). Open collector: Voltage of 0.5 VDC or less when ON, leakage current of 0.5 mA or less when OFF Non-voltage contact: Contact resistance of 200 $\Omega$ or less when ON, 50 k $\Omega$ or more when OFF Linear scaling, differential calculations 12 VDC, 20 mA or more Approx. 2.4 k $\Omega$ 1 (1 common per 8 channels) 10 V Between input terminals and internal circuitry: 20 M $\Omega$ or greater (at 500 VDC) Between input terminals and internal circuitry: 1500 VAC, 1 minute cotton 6 Relay contact (c contact) 150 VAC or less when connected to the main circuit (first-order power
Digital input (DI) section inputs: Input format: Range types: ON/OFF detection:  Input calculation: Contact rating: Input resistance: No. of common: Allowable input voltage: Insulation resistance: Withstand voltage:     Digital output (DO) secont outputs: Output format: Rated load voltage:  Max. load current:	One allowed the context of the cont
Digital input (DI) section Inputs: Inputs: Input format: Range types: ON/OFF detection:  Input calculation: Contact rating: Input resistance: No. of common: Allowable input voltage: Insulation resistance: Withstand voltage:     Digital output (DO) section Output format: Rated load voltage:  Max. load current: Min. load voltage/current:	Open collector or non-voltage contact DI, pulse (250Hz (The chattering filter: OFF), 125Hz (The chattering filter: ON), min. pulse width: 2 ms, requires the MATH (optional code /MTI). Open collector: Voltage of 0.5 VDC or less when ON, leakage current of 0.5 mA or less when OFF Non-voltage contact: Contact resistance of 200 $\Omega$ or less when ON, 50 k $\Omega$ or more when OFF Linear scaling, differential calculations 12 VDC, 20 mA or more Approx. 2.4 k $\Omega$ 1 (1 common per 8 channels) 10 V Between input terminals and internal circuitry: 20 M $\Omega$ or greater (at 500 VDC) Between input terminals and internal circuitry: 1500 VAC, 1 minute Ction 6 Relay contact (c contact) 150 VAC or less when connected to the main circuit (first-order power supply) 250 VAC or less when connected to a circuit derived from the main circuit (second-order power supply), or 30 VDC or less 2 A (DC)/2 A (AC), resistive load, each 5 VDC/10 mA
Digital input (DI) section Inputs: Input format: Range types: ON/OFF detection:  Input calculation: Contact rating: Input resistance: No. of common: Allowable input voltage: Insulation resistance: Withstand voltage:     Digital output (DO) secont outputs: Output format: Rated load voltage:  Max. load current:	Open collector or non-voltage contact DI, pulse (250Hz (The chattering filter: OFF), 125Hz (The chattering filter: ON), min. pulse width: 2 ms, requires the MATH (optional code /MT)). Open collector: Voltage of 0.5 VDC or less when ON, leakage current of 0.5 mA or less when OFF Non-voltage contact: Contact resistance of 200 $\Omega$ or less when ON, 50 $k\Omega$ or more when OFF Linear scaling, differential calculations 12 VDC, 20 mA or more Approx. 2.4 $k\Omega$ 1 (1 common per 8 channels) 10 V Between input terminals and internal circuitry: 20 M $\Omega$ or greater (at 500 VDC) Between input terminals and internal circuitry: 1500 VAC, 1 minute circuitors (contact) 150 VAC or less when connected to the main circuit (first-order power supply) 250 VAC or less when connected to a circuit derived from the main circuit (second-order power supply), or 30 VDC or less 5 VDC/10 mA (call outputs independent) Between output terminals and internal circuitry: 20 M $\Omega$ or greater (all outputs independent) Between output terminals and internal circuitry: 20 M $\Omega$ or greater
Digital input (DI) section Inputs: Inputs: Input format: Range types: ON/OFF detection:  Input calculation: Contact rating: Input resistance: No. of common: Allowable input voltage: Insulation resistance: Withstand voltage:     Digital output (DO) section Outputs: Outputs: Output format: Rated load voltage:  Max. load current: Min. load voltage/current: No. of common: Insulation resistance:	Open collector or non-voltage contact DI, pulse (250Hz (The chattering filter: OFF), 125Hz (The chattering filter: ON), min. pulse width: 2 ms, requires the MATH (optional code /MTJ). Open collector: Voltage of 0.5 VDC or less when ON, leakage current of 0.5 mA or less when OFF Non-voltage contact: Contact resistance of 200 $\Omega$ or less when ON, 50 k $\Omega$ or more when OFF Linear scaling, differential calculations 12 VDC, 20 mA or more Approx. 2.4 k $\Omega$ 1 (1 common per 8 channels) 10 V Between input terminals and internal circuitry: 20 M $\Omega$ or greater (at 500 VDC) Between input terminals and internal circuitry: 1500 VAC, 1 minute ction 6 Relay contact (c contact) 150 VAC or less when connected to the main circuit (first-order power supply) 250 VAC or less when connected to a circuit derived from the main circuit (second-order power supply), or 30 VDC or less 2 A (DC)/2 A (AC), resistive load, each 5 VDC/10 mA 6 (all outputs independent) Between output terminals and internal circuitry: 20 M $\Omega$ or greater (at 500 VDC)
Digital input (DI) section Inputs: Inputs: Input format: Range types: ON/OFF detection:  Input calculation: Contact rating: Input resistance: No. of common: Allowable input voltage: Insulation resistance: Withstand voltage:     Digital output (DO) section Output format: Rated load voltage:  Max. load current: Min. load voltage/current: No. of common: Insulation resistance: Withstand voltage:	Open collector or non-voltage contact DI, pulse (250Hz (The chattering filter: OFF), 125Hz (The chattering filter: ON), min. pulse width: 2 ms, requires the MATH (optional code /MTI). Open collector: Voltage of 0.5 VDC or less when ON, leakage current of 0.5 mA or less when OFF Non-voltage contact: Contact resistance of 200 Ω or less when ON, 50 kΩ or more when OFF Linear scaling, differential calculations 12 VDC, 20 mA or more Approx. 2.4 kΩ 1 (1 common per 8 channels) 10 V Between input terminals and internal circuitry: 20 MΩ or greater (at 500 VDC) Between input terminals and internal circuitry: 1500 VAC, 1 minute   **Ction** 6 Relay contact (c contact) 150 VAC or less when connected to the main circuit (first-order power supply) 250 VAC or less when connected to a circuit derived from the main circuit (second-order power supply), or 30 VDC or less 2 A (DC)/2 A (AC), resistive load, each 5 VDC/10 mA 6 (all outputs independent) Between output terminals and internal circuitry: 20 MΩ or greater (at 500 VDC) Between output terminals and internal circuitry: 20 MΩ or greater (at 500 VDC) Between output terminals and internal circuitry: 2700 VAC, 1 minute
Digital input (DI) section Inputs: Inputs: Input format: Range types: ON/OFF detection:  Input calculation: Contact rating: Input resistance: No. of common: Allowable input voltage: Insulation resistance: Withstand voltage:     Digital output (DO) section Outputs: Outputs: Output format: Rated load voltage:  Max. load current: Min. load voltage/current: No. of common: Insulation resistance:	Open collector or non-voltage contact DI, pulse (250Hz (The chattering filter: OFF), 125Hz (The chattering filter: ON), min. pulse width: 2 ms, requires the MATH (optional code /MTI). Open collector: Voltage of 0.5 VDC or less when ON, leakage current of 0.5 mA or less when OFF Non-voltage contact: Contact resistance of 200 Ω or less when ON, 50 kΩ or more when OFF Linear scaling, differential calculations 12 VDC, 20 mA or more Approx. 2.4 kΩ 1 (1 common per 8 channels) 10 V Between input terminals and internal circuitry: 20 MΩ or greater (at 500 VDC) Between input terminals and internal circuitry: 1500 VAC, 1 minute   **Ction** 6 Relay contact (c contact) 150 VAC or less when connected to the main circuit (first-order power supply) 250 VAC or less when connected to a circuit derived from the main circuit (second-order power supply), or 30 VDC or less 2 A (DC)/2 A (AC), resistive load, each 5 VDC/10 mA 6 (all outputs independent) Between output terminals and internal circuitry: 20 MΩ or greater (at 500 VDC) Between output terminals and internal circuitry: 20 MΩ or greater (at 500 VDC) Between output terminals and internal circuitry: 2700 VAC, 1 minute
Digital input (DI) section Inputs: Inputs: Input format: Range types: ON/OFF detection:  Input calculation: Contact rating: Input resistance: No. of common: Allowable input voltage: Insulation resistance: Withstand voltage:     Digital output (DO) section Output format: Rated load voltage:  Max. load current: Min. load voltage/current: No. of common: Insulation resistance: Withstand voltage:	Open collector or non-voltage contact DI, pulse (250Hz (The chattering filter: OFF), 125Hz (The chattering filter: ON), min. pulse width: 2 ms, requires the MATH (optional code /MTI). Open collector: Voltage of 0.5 VDC or less when ON, leakage current of 0.5 mA or less when OFF Non-voltage contact: Contact resistance of 200 Ω or less when ON, 50 kΩ or more when OFF Linear scaling, differential calculations 12 VDC, 20 mA or more Approx. 2.4 kΩ 1 (1 common per 8 channels) 10 V Between input terminals and internal circuitry: 20 MΩ or greater (at 500 VDC) Between input terminals and internal circuitry: 1500 VAC, 1 minute   **Ction** 6 Relay contact (c contact) 150 VAC or less when connected to the main circuit (first-order power supply) 250 VAC or less when connected to a circuit derived from the main circuit (second-order power supply), or 30 VDC or less 2 A (DC)/2 A (AC), resistive load, each 5 VDC/10 mA 6 (all outputs independent) Between output terminals and internal circuitry: 20 MΩ or greater (at 500 VDC) Between output terminals and internal circuitry: 20 MΩ or greater (at 500 VDC) Between output terminals and internal circuitry: 2700 VAC, 1 minute
Digital input (DI) section Inputs: Inputs: Input format: Range types: ON/OFF detection:  Input calculation: Contact rating: Input resistance: No. of common: Allowable input voltage: Insulation resistance: Withstand voltage:     Digital output (DO) section outputs: Outputs: Rated load voltage:  Max. load current: Min. load voltage/current: No. of common: Insulation resistance: Withstand voltage: Withstand voltage: Withstand voltage:  GX90XP Pulse Input Metals in the public input Metals input Metals in the public input Metals	Open collector or non-voltage contact DI, pulse (250Hz (The chattering filter: OFF), 125Hz (The chattering filter: ON), min. pulse width: 2 ms, requires the MATH (optional code /MT)). Open collector: Voltage of 0.5 VDC or less when ON, leakage current of 0.5 mA or less when OFF Non-voltage contact: Contact resistance of 200 $\Omega$ or less when ON, 50 k $\Omega$ or more when OFF Linear scaling, differential calculations 12 VDC, 20 mA or more Approx. 2.4 k $\Omega$ 1 (1 common per 8 channels) 10 V Between input terminals and internal circuitry: 20 M $\Omega$ or greater (at 500 VDC) Between input terminals and internal circuitry: 1500 VAC, 1 minute ction 6 Relay contact (c contact) 150 VAC or less when connected to the main circuit (first-order power supply) 250 VAC or less when connected to a circuit derived from the main circuit (second-order power supply), or 30 VDC or less 2 A (DC)/2 A (AC), resistive load, each 5 VDC/10 mA 6 (all outputs independent) Between output terminals and internal circuitry: 20 M $\Omega$ or greater (at 500 VDC) Between output terminals and internal circuitry: 20 M $\Omega$ or greater (at 500 VDC) Between output terminals and internal circuitry: 2700 VAC, 1 minute odule
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Digital input (DI) section Inputs: Inputs: Input format: Range types: ON/OFF detection:  Input calculation: Contact rating: Input resistance: No. of common: Allowable input voltage: Insulation resistance: Withstand voltage:     Digital output (DO) section outputs: Rated load voltage:  Max. load current: Min. load voltage/current: No. of common: Insulation resistance: Withstand voltage:  GX90XP Pulse Input M Number of inputs: Measurement interval: Input type: Input range: Minimum detection pulse	Open collector or non-voltage contact DI, pulse (250Hz (The chattering filter: OFF), 125Hz (The chattering filter: ON), min. pulse width: 2 ms, requires the MATH (optional code /MT)). Open collector: Voltage of 0.5 VDC or less when ON, leakage current of 0.5 mA or less when OFF Non-voltage contact: Contact resistance of 200 $\Omega$ or less when ON, 50 k $\Omega$ or more when OFF Linear scaling, differential calculations 12 VDC, 20 mA or more Approx. 2.4 k $\Omega$ 1 (1 common per 8 channels) 10 V Between input terminals and internal circuitry: 20 M $\Omega$ or greater (at 500 VDC) Between input terminals and internal circuitry: 1500 VAC, 1 minute ction 6 Relay contact (c contact) 150 VAC or less when connected to the main circuit (first-order power supply) 250 VAC or less when connected to a circuit derived from the main circuit (second-order power supply), or 30 VDC or less 2 A (DC)/2 A (AC), resistive load, each 5 VDC/10 mA 6 (all outputs independent) Between output terminals and internal circuitry: 20 M $\Omega$ or greater (at 500 VDC) Between output terminals and internal circuitry: 2700 VAC, 1 minute odule 10 100 ms (shortest) Contact (open collector, voltage-free contact), level (5 V logic) Up to 20 kHz 30 Hz when the chattering filter is in use (On) 55 ms when the chattering filter is in use (On) 55 ms when the chattering filter is in use (On) 55 ms when the chattering filter is in use (On)
Digital input (DI) section Inputs: Inputs: Input format: Range types: ON/OFF detection:  Input calculation: Contact rating: Input resistance: No. of common: Allowable input voltage: Insulation resistance: Withstand voltage: Digital output (DO) sectory of the property o	Open collector or non-voltage contact DI, pulse (250Hz (The chattering filter: OFF), 125Hz (The chattering filter: ON), min. pulse width: 2 ms, requires the MATH (optional code /MT)). Open collector: Voltage of 0.5 VDC or less when ON, leakage current of 0.5 mA or less when OFF Non-voltage contact: Contact resistance of 200 Ω or less when ON, 50 kΩ or more when OFF Linear scaling, differential calculations 12 VDC, 20 mA or more Approx. 2.4 kΩ 1 (1 common per 8 channels) 10 V Between input terminals and internal circuitry: 20 MΩ or greater (at 500 VDC) Between input terminals and internal circuitry: 1500 VAC, 1 minute  ction 6 Relay contact (c contact) 150 VAC or less when connected to the main circuit (first-order power supply) 250 VAC or less when connected to a circuit derived from the main circuit (second-order power supply), or 30 VDC or less 2 A (DC)/2 A (AC), resistive load, each 5 VDC/10 mA 6 (all outputs independent) Between output terminals and internal circuitry: 20 MΩ or greater (at 500 VDC) Between output terminals and internal circuitry: 2700 VAC, 1 minute  odule  10 100 ms (shortest) Contact (open collector, voltage-free contact), level (5 V logic) Up to 20 kHz 30 Hz when the chattering filter is in use (On)
● Digital input (DI) section Inputs: Inputs: Input format: Range types: ON/OFF detection:  Input calculation: Contact rating: Input resistance: No. of common: Allowable input voltage: Insulation resistance: Withstand voltage: ● Digital output (DO) sectory output format: Rated load voltage:  Max. load current: Min. load voltage: Withstand voltage:  Withstand voltage:  Max. load current: Min. load voltage/current: No. of common: Insulation resistance: Withstand voltage:  GX90XP Pulse Input Minumber of inputs: Measurement interval: Input type: Input range: Minimum detection pulse width: Measurement accuracy:	Open collector or non-voltage contact DI, pulse (250Hz (The chattering filter: OFF), 125Hz (The chattering filter: ON), min. pulse width: 2 ms, requires the MATH (optional code /MTI). Open collector: Voltage of 0.5 VDC or less when ON, leakage current of 0.5 mA or less when OFF Non-voltage contact: Contact resistance of 200 Ω or less when ON, 50 kΩ or more when OFF Linear scaling, differential calculations 12 VDC, 20 mA or more Approx. 2.4 kΩ 1 (1 common per 8 channels) 10 V Between input terminals and internal circuitry: 20 MΩ or greater (at 500 VDC) Between input terminals and internal circuitry: 1500 VAC, 1 minute  **Ction** 6 Relay contact (c contact) 150 VAC or less when connected to the main circuit (first-order power supply) 250 VAC or less when connected to a circuit derived from the main circuit (second-order power supply), or 30 VDC or less 2 A (DC)/2 A (AC), resistive load, each 5 VDC/10 mA 6 (all outputs independent) Between output terminals and internal circuitry: 20 MΩ or greater (at 500 VDC) Between output terminals and internal circuitry: 2700 VAC, 1 minute  odule  10 100 ms (shortest) Contact (open collector, voltage-free contact), level (5 V logic) Up to 20 kHz 30 Hz when the chattering filter is in use (On)  25 μs 15 ms when the chattering filter is in use (On)  Count ± 1 pulse During integration, the following accuracies are added. Upon MATH start: +1 measuring period 4 Integration requires the math function (optional code /MT).
Digital input (DI) section Inputs: Inputs: Input format: Range types: ON/OFF detection:  Input calculation: Contact rating: Input resistance: No. of common: Allowable input voltage: Insulation resistance: Withstand voltage: Digital output (DO) sectory of the property o	Open collector or non-voltage contact DI, pulse (250Hz (The chattering filter: OFF), 125Hz (The chattering filter: ON), min. pulse width: 2 ms, requires the MATH (optional code /MT)). Open collector: Voltage of 0.5 VDC or less when ON, leakage current of 0.5 mA or less when OFF Non-voltage contact: Contact resistance of 200 $\Omega$ or less when ON, 50 $k\Omega$ or more when OFF Linear scaling, differential calculations 12 VDC, 20 mA or more Approx. 2.4 $k\Omega$ (11 common per 8 channels) 10 V Between input terminals and internal circuitry: 20 M $\Omega$ or greater (at 500 VDC) Between input terminals and internal circuitry: 1500 VAC, 1 minute ction 6 Relay contact (c contact) 130 VAC or less when connected to the main circuit (first-order power supply) 250 VAC or less when connected to a circuit derived from the main circuit (second-order power supply), or 30 VDC or less 2 A (DC)/2 A (AC), resistive load, each 5 VDC/10 mA 6 (all outputs independent) Between output terminals and internal circuitry: 20 M $\Omega$ or greater (at 500 VDC) Between output terminals and internal circuitry: 2700 VAC, 1 minute odule 10 100 ms (shortest) Contact (open collector, voltage-free contact), level (5 V logic) Up to 20 kHz 30 Hz when the chattering filter is in use (On) 25 µs 15 ms when the chattering filter is in use (On) Count $\pm$ 1 pulse During integration, the following accuracies are added. Upon MATH stop: -1 measuring period
● Digital input (DI) section Inputs: Input communication input (DI) section input (DI) s	Open collector or non-voltage contact DI, pulse (250Hz (The chattering filter: OFF), 125Hz (The chattering filter: ON), min. pulse width: 2 ms, requires the MATH (optional code /MT)). Open collector: Voltage of 0.5 VDC or less when ON, leakage current of 0.5 mA or less when OFF Non-voltage contact: Contact resistance of 200 $\Omega$ or less when ON, 50 k $\Omega$ or more when OFF Linear scaling, differential calculations 12 VDC, 20 mA or more Approx. 2.4 k $\Omega$ 1 (1 common per 8 channels) 10 V Between input terminals and internal circuitry: 20 M $\Omega$ or greater (at 500 VDC) Between input terminals and internal circuitry: 1500 VAC, 1 minute cotton 6 Relay contact (c contact) 150 VAC or less when connected to the main circuit (first-order power supply) 250 VAC or less when connected to a circuit derived from the main circuit (second-order power supply), or 30 VDC or less 2 A (DC)/2 A (AC), resistive load, each 5 VDC/10 mA 6 (all outputs independent) Between output terminals and internal circuitry: 20 M $\Omega$ or greater (at 500 VDC) Between output terminals and internal circuitry: 2700 VAC, 1 minute odule 10 ms (shortest) Contact (open collector, voltage-free contact), level (5 V logic) Up to 20 kHz 30 Hz when the chattering filter is in use (On) 25 µs 15 ms when the chattering filter is in use (On) Count $\pm$ 1 pulse During integration, the following accuracies are added. Upon MATH stor: -1 measuring period 1 Integration requires the math function (optional code /MT). Removes chattering up to 5 ms (can be turned on/off on each channel) Approx. 0.2 V Contact: 15 V DC or higher and 30 mA or higher rating. Minimum applicable load current 1 mA or less.
Digital input (DI) section inputs: Input calculation: Range types: ON/OFF detection:  Input calculation: Contact rating: Input resistance: No. of common: Allowable input voltage: Insulation resistance: Withstand voltage:     Digital output (DO) sectory of the properties of the	Open collector or non-voltage contact DI, pulse (250Hz (The chattering filter: OFF), 125Hz (The chattering filter: ON), min. pulse width: 2 ms, requires the MATH (optional code /MTI). Open collector: Voltage of 0.5 VDC or less when ON, leakage current of 0.5 mA or less when OFF Non-voltage contact: Contact resistance of 200 Ω or less when ON, 50 kΩ or more when OFF Linear scaling, differential calculations 12 VDC, 20 mA or more Approx. 2.4 kΩ 1 (1 common per 8 channels) 10 V Between input terminals and internal circuitry: 20 MΩ or greater (at 500 VDC) Between input terminals and internal circuitry: 1500 VAC, 1 minute  **Ction** 6 Relay contact (c contact) 150 VAC or less when connected to the main circuit (first-order power supply) 250 VAC or less when connected to a circuit derived from the main circuit (second-order power supply), or 30 VDC or less 2 A (DC)/2 A (AC), resistive load, each 5 VDC/10 mA 6 (all outputs independent) Between output terminals and internal circuitry: 2700 VAC, 1 minute  **Odule** 10 100 ms (shortest) Contact (open collector, voltage-free contact), level (5 V logic) Up to 20 kHz 30 Hz when the chattering filter is in use (On) Count ± 1 pulse During integration, the following accuracies are added. Upon MATH start: +1 measuring period Upon MATH stop: -1 measuring period Upon
● Digital input (DI) section Inputs: Inputs: Input format: Range types: ON/OFF detection:  Input calculation: Contact rating: Input resistance: No. of common: Allowable input voltage: Insulation resistance: Withstand voltage:  ● Digital output (DO) sectory outputs: Outputs: Output format: Rated load voltage/current: No. of common: Insulation resistance: Withstand voltage:  GX90XP Pulse Input M Number of inputs: Measurement interval: Input range: Minimum detection pulse width: Measurement accuracy: Chattering filter: Hysteresis width: Contact, transistor rating:	Open collector or non-voltage contact DI, pulse (250Hz (The chattering filter: OFF), 125Hz (The chattering filter: ON), min. pulse width: 2 ms, requires the MATH (optional code /MT)). Open collector: Voltage of 0.5 VDC or less when ON, leakage current of 0.5 mA or less when OFF Non-voltage contact: Contact resistance of 200 Ω or less when ON, 50 kΩ or more when OFF Linear scaling, differential calculations 12 VDC, 20 mA or more Approx. 2.4 kΩ 1 (1 common per 8 channels) 10 V Between input terminals and internal circuitry: 20 MΩ or greater (at 500 VDC) Between input terminals and internal circuitry: 1500 VAC, 1 minute  ction 6 Relay contact (c contact) 150 VAC or less when connected to the main circuit (first-order power supply) 250 VAC or less when connected to a circuit derived from the main circuit (second-order power supply), or 30 VDC or less 2 A (DC)/2 A (AC), resistive load, each 5 VDC/10 mA 6 (all outputs independent) Between output terminals and internal circuitry: 20 MΩ or greater (at 500 VDC) Between output terminals and internal circuitry: 2700 VAC, 1 minute  odule  10 100 ms (shortest) Contact (open collector, voltage-free contact), level (5 V logic) Up to 20 kHz 30 Hz when the chattering filter is in use (On) 25 μs 15 ms when the chattering filter is in use (On) Count ± 1 pulse During integration, the following accuracies are added. Upon MATH stor: -1 measuring period Upon MATH stor: -1 measuring period Upon MATH stor: -1 measuring period 10 Integration requires the math function (optional code /MT). Removes chattering up to 5 ms (can be turned on/off on each channel) Approx. 0.2 V Contact: 15 V DC or higher and 30 mA or higher rating. Minimum applicable load current 1 mA or less. Transistor: With the following ratings: Vce>15 VDC, Ic>30 mA ± 10 V DC Between input terminals and internal circuitry:
Digital input (DI) section inputs: Inputs: Input format: Range types: ON/OFF detection:  Input calculation: Contact rating: Input resistance: No. of common: Allowable input voltage: Insulation resistance: Withstand voltage: Digital output (DO) sectory output format: Rated load voltage:  Max. load current: Min. load voltage/current: No. of common: Insulation resistance: Withstand voltage:  GX90XP Pulse Input Monumber of inputs: Measurement interval: Input type: Input proge: Input range: Minimum detection pulse width: Measurement accuracy:  Chattering filter: Hysteresis width: Contact, transistor rating:  Maximum input voltage:	Open collector or non-voltage contact DI, pulse (250Hz (The chattering filter: OFF), 125Hz (The chattering filter: ON), min. pulse width: 2 ms, requires the MATH (optional code /MT)). Open collector: Voltage of 0.5 VDC or less when ON, leakage current of 0.5 mA or less when OFF Non-voltage contact: Contact resistance of 200 Ω or less when ON, 50 kΩ or more when OFF Linear scaling, differential calculations 12 VDC, 20 mA or more Approx. 2.4 kΩ 1 (1 common per 8 channels) 10 V Between input terminals and internal circuitry: 20 MΩ or greater (at 500 VDC) Between input terminals and internal circuitry: 1500 VAC, 1 minute  ction 6 Relay contact (c contact) 150 VAC or less when connected to the main circuit (first-order power supply) 250 VAC or less when connected to a circuit derived from the main circuit (second-order power supply), or 30 VDC or less 2 A (DC)/2 A (AC), resistive load, each 5 VDC/10 mA 6 (all outputs independent) Between output terminals and internal circuitry: 2700 VAC, 1 minute  cutil and the proper supply (at 500 VDC) Between output terminals and internal circuitry: 2700 VAC, 1 minute  cutil second-order power supply), or 30 VDC or less 2 A (DC)/2 A (AC), resistive load, each 5 VDC/10 mA 6 (all outputs independent) Between output terminals and internal circuitry: 2700 VAC, 1 minute  cutil second-order power supply in the proper supply or greater (at 500 VDC) Between output terminals and internal circuitry: 2700 VAC, 1 minute  cutil second-order power supply in the proper supply or greater (at 500 VDC)  Between output terminals and internal circuitry: 2700 VAC, 1 minute  cutil second-order power supply or 30 VDC or less 2 A (DC) or second-order power supply or 30 VDC order second-order seco

Analog outp	ut module	GX90YA			
Number of outpu	ıts:	4 (isolated between channels)			
Output type:		4 to 20mA or 0 to 20mA			
Output update in Load resistance:	itervai:	100 ms (shortest) 600 $\Omega$ or less			
Output accuracy:		± 0.1% of F.S. (1mA or more) (F.S.=20mA)			
PID control	module GX	(90UT			
<ul><li>Control loo</li></ul>					
Number of loops		2			
<ul><li>Analog input</li></ul>	ut (measur	ed input)			
Measured points		2			
Measurement typ	pe:	DC voltage (DCV)/standardized signal, TC/RTD, DI (LEVEL and non-voltage contact)			
Scan (control) int	erval :	100 ms or 200 ms (system global setting)			
Analog out	put (contro	l output/transmission output/sensor power supply)			
Outputs: Output type:		2 Power supply for current, voltage pulse, or sensors.			
output type.		Current output: 4–20 mA or 0–20 mA			
		Voltage pulse output: ON voltage = 12 VDC or more (load resistance 600			
		Ω or more), OFF voltage = 0.1 VDC or less Can be used as a sensor power supply (13.0–18.3 VDC)			
Digital inpu	ıt (switchin	g the SP, operation mode, etc.)			
Inputs:		8			
Input format:		Non-voltage contact and open collector Contact rating: 12 VDC or more, 20 mA or more			
Digital outs	out (of alar	ms, events, etc.)			
Outputs:		8			
Output format:		Open collector (sink type)			
Output contact co Withstand voltage		Max 24 VDC, 50 mA See PID control module general specifications (GS 04L51B01-31EN)			
resistance:					
Terminal type: Weight:		M3 screw terminals Approximately 0.3kg			
	ancion Mo	, ,			
GX90EX Expa					
between subu		ommunication between main unit and subunits, and			
Communication		10Base-T/100Base-TX (Auto)			
Ports: Connection cable		2 STP cable, CAT5 or later			
		: Cascade connection (no ring connection)			
Communication i	range:	100 m			
GX90NW Ne	twork Mod	dule			
Ethernet po	ort				
Communication	speed:	10BASE-T/100BASE-TX (Auto)			
Port: Connection cable	<u>:</u>	2 ports STP cable, CAT5 or later			
Communication i	range:	100m			
PROFINET					
Communication s Port:	speea:	100BASE-TX full duplex 2 ports			
Connection cable		PROFINET communication cable			
Communication I		100m Type: PROFINET IO-Device			
PROFINET comm specifications:	uriication	Conformance class: B			
		Support for periodic and aperiodic communication			
SMARTDAC+	GM comm	non specifications			
Standards sup	ported				
CSA:		2.2 No. 61010-1, overvoltage category II or I, pollution degree 2,			
		2.2 No. 61010-2-030 C 61010-2-201			
UL;	UL 61010-1,	UL 61010-2-030 (CSA NRTL/C)			
CE/EMC		201(CSA NRTL/C) ompliance, Class A Table 2, EN61000-3-2 compliance,			
directives:	EN61000-3-3	3 compliance, EN55011 Class A Group 1			
		EN 61010-2-030, overvoltage category II or I, pollution degree 2 nt category II, EN 61010-2-201 compliance			
directive: /C8 option	HEALTH&SA				
RE directive:		EN61010-2-030 compliance			
		Overvoltage category II or I, pollution degree 2 Measurement category II			
		EN62311 compliance			
	EMC	EN301 489-1 compliance EN301 489-17 compliance			
		EN61326-1 compliance			
	SPECTRUM	EN300 328 compliance			
		in Australia and New Zealand (RCM): EN55011 Class A Group 1 dards of Australia and New Zealand (RCM) (optional code /C8):			
AS/NZS4268, AS/					
KC marking:		Electromagnetic wave interference prevention standard, electromagnetic wave protection standard compliance			
Environmental pe	erformance:	WEEE directive support			
Wireless (Bluetoc	oth):	Supports radio wave regulations of Japan, America, Canada, Europe (EU			
		Australia, New Zealand, China, and Korea.			
Normal opera	ting condit	ions			
Ambient tempera	ature:	-20 to 60°C			
		If less, -20 to 50°C · When using the GX90YD, GX90WD, and GX90XA-T1			
		(electromagnetic relay type)			
Ambient humidit	v:	With the GM10/C8 (Bluetooth option)  Understand the GM10/C8 (Bluetooth option)  Understand the GM10/C8 (Bluetooth option)			
Vibration:	×:	5 ≤ f < 8.4 Hz amplitude 3.5 mm (peak)			
Shock:		$8.4 \le f \le 160$ Hz acceleration 9.8 m/s <sup>2</sup> (or less) When ON, 98 m/s <sup>2</sup> or less, 11 ms, 3 times in 6 directions ( $\pm X$ , $\pm Y$ , $\pm Z$ ),			
Shock:		when ON, 98 m/s or less, 11 ms, 3 times in 6 directions ( $\pm x$ , $\pm y$ , $\pm z$ ), (excluding GX90YD and GX90WD)			
		When OFF, 500 m/s <sup>2</sup> or less, approx. 10 ms, 3 times in 6 directions			
Magnetic field:		(±X, ±Y, ±Z) 400 A/m or less (DC and 50/60 Hz)			



## Main measurement range and accuracy\*1

Universal, Current (mA) input, Low withstand voltage relay, Electromagnetic relay, 4-wire RTD/resister, High withstand voltage type

Transit time		Measurement range	Measurement accuracy			
Input type	Range		A/D integration time: 16.7ms or more*2			
	20mV	-20.000	to 20.000 mV	±(0.05 % of rdg +12 μV)	±(0.1 % of rdg +40 μV)	
	60mV	-60.00	to 60.00 mV	±(0.05 % of rdg +0.03 mV)	±(0.1 % of rdg +0.15 mV)	
	200mV	-200.00	to 200.00 mV	±(0.05 % of rdg +0.03 mV)	±(0.1 % of rdg +0.4 mV)	
	1V	-1.0000	to 1.0000 V	±(0.05 % of rdg +1.2 mV)	±(0.1 % of rdg +4 mV)	
DCV	2V	-2.0000	to 2.0000 V	±(0.05 % of rdg +1.2 mV)	±(0.1 % of rdg +4 mV)	
	6V	-6.000	to 6.000 V	±(0.05 % of rdg +3 mV)	±(0.1 % of rdg +15 mV)	
			±(0.05 % of rdg +3 mV)	±(0.1 % of rdg +40 mV)		
	50V	-50.00	to 50.00 V	±(0.05 % of rdg +0.03 V)	±(0.1 % of rdg +0.15 V)	
	0.4-2V	0.3200	to 2.0800 V	±(0.05 % of rdg +1.2 mV)	±(0.1 % of rdg +4 mV)	
standard signal	1-5V	0.800	to 5.200 V	±(0.05 % of rdg +3 mV)	±(0.1 % of rdg +15 mV)	
OC current	0-20mA	0.000	to 20.000mA			
OC current standard signal)	4-20mA	3.200	to 20.800mA	$\pm$ (0.3 % of rdg +5 $\mu$ A)	$\pm$ (0.3 % of rdg +90 $\mu$ A)	
, , , , , , , , , , , , , , , , , , ,	R	0.0	to 1760.0°C	±(0.15 % of rdg +1.0°C)	±(0.2 % of rdg +6.0°C)	
	S	0.0	to 1760.0°C	However, R, S; 0.0 to 800.0°C: ± 2.2°C B; 400.0 to 800.0°C: ± 3.0°C	However, R, S; 0.0 to 800.0°C: ± 7.6°C	
	В	0.0	to 1820.0°C		B; 400.0 to 800.0°C: ± 11.0°C Accuracy at less than 400.0°C not guaranteed	
		-270.0	to 1370.0°C	±(0.15 % of rdg +0.7°C)	±(0.2 % of rdg +5.0°C)	
TC (Excluding	К	-200.0	to 500.0°C	However, -200.0 to 0.0°C: ±(0.35 % of rdg +0.7°C)	However, -200.0 to 0.0°C: ±(3 % of rdg +5.0°C) Accuracy at less than -200.0°C not guaranteed	
	E	-270.0	to 800.0°C	±(0.15 % of rdg +0.5°C)	±(0.2 % of rdg +4.0°C)	
	J	-200.0	to 1100.0°C	However, -200.0 to 0.0 °C: ±(0.35 % of rdg +0.5 °C) Accuracy at less than -200.0 °C not guaranteed	However, -200.0 to 0.0°C: ±(2 % of rdg +4.0°C) Accuracy at less than -200.0°C not guaranteed	
	т	-270.0	to 400.0°C	±(0.15 % of rdg +0.5°C) However, -200.0 to 0.0°C: ±(0.35 % of rdg +0.5°C) Accuracy at less than -200.0°C not guaranteed	±(0.2 % of rdg +2.5°C) However, -200.0 to 0.0°C: ±(2 % of rdg +2.5°C) Accuracy at less than -200.0°C not guaranteed	
RJC accuracy)	N	-270.0	to 1300.0°C	±(0.15 % of rdg +0.7°C) However, -200.0 to 0.0°C: ±(0.7 % of rdg +0.7°C) Accuracy at less than -200.0°C not guaranteed	±(0.3 % of rdg +6.0°C) However, -200.0 to 0.0°C: ±(5 % of rdg +6.0°C) Accuracy at less than -200.0°C not guaranteed	
	W	0.0	to 2315.0°C	±(0.15 % of rdg +1.5°C)	±(0.3 % of rdg +14.0°C) However, 1000.0°C or more: ±(0.8 % of rdg +9.0 °C)	
	L	-200.0	to 900.0°C	±(0.15 % of rdg +0.5°C) Less than 0.0°C: ±(0.5 % of rdg +0.5°C)	±(0.2 % of rdg +4.0°C) Less than 0.0°C: ±(3 % of rdg +4.0°C)	
	U	-200.0	to 400.0°C	±(0.15 % of rdg +0.5°C) Less than 0.0°C: ±(0.7 % of rdg +0.5°C)	±(0.2 % of rdg +2.5°C) Less than 0.0°C: ±(3 % of rdg +2.5°C)	
	WRe3-25	0.0	to 2320.0°C	±(0.2 % of rdg +2.5°C)	± 18.0°C 2000.0°C or more: ± 0.9 % of rdg	
	D.100	-200.0	to 850.0°C			
TD .	Pt100	-150.00	to 150.00°C	1,005,005,000	1,020, 51,4505)	
Measured urrent: 1 mA)		-200.0	to 550.0°C	±(0.05 % of rdg+0.3°C)	±(0.3 % of rdg+1.5°C)	
urrent. rina)	JPt100	-150.00	to 150.00°C			
		-200.0	to 850.0°C			
-wire RTD	Pt100	-150.00	to 150.00°C		142	
Measured		-200.0	to 550.0°C	±(0.05 % of rdg+0.3°C)	±(0.1 % of rdg+1.5°C)	
urrent: 1 mA)	JPt100	-150.00	to 150.00°C			
-wire RTD	Pt500	-200.0	to 850.0°C			
Measured current: 0.25 mA)	Pt1000	-200.0	to 850.0°C	±(0.05 % of rdg+0.3°C)	±(0.1 % of rdg+1.5°C)	
	20 Ω (Measured current: 1mA)	0.000	to 20.000 Ω	±(0.05 % of rdg+0.007 Ω)	±(0.1 % of rdg+0.025 Ω)	
Resistance	200 Ω (Measured current: 1mA)	0.00	to 200.00 Ω	$\pm$ (0.05 % of rdg+0.03 Ω)	$\pm$ (0.1 % of rdg+0.15 Ω)	
(4-wire)	2000 Ω (Measured current: 0.25mA)	0.0	to 2000.0 Ω	$\pm$ (0.05 % of rdg+0.3 $\Omega$ )	$\pm$ (0.1 % of rdg+1.0 $\Omega$ )	
	Level			Threshold level (Vth=2.4 V) accuracy ± 0.1 V		
OI .						

#### High-speed universal type

			Measurem	ent accuracy				
Input type	Range		Scan interval: 50 ms or more (Only the Values in [ ] apply when the scan interval is 50/100/200 ms)	Scan interval: 20 ms or less (Only the Values in [ ] apply when the scan interval is 1/2/5 ms)				
	20 mV	-20.000 to 20.000 mV	$\pm$ (0.05 % of rdg+5[12] $\mu$ V)	$\pm$ (0.1 % of rdg+25[40] $\mu$ V)				
	60 mV	-60.00 to 60.00 mV	±(0.05 % of rdg+0.02 mV)	±(0.1 % of rdg+0.1 mV)				
	200 mV	-200.00 to 200.00 mV	±(0.05 % of rdg+0.02[0.03] mV)	±(0.1 % of rdg+0.1[0.4] mV)				
	1 V	-1.0000 to 1.0000 V	±(0.05 % of rdg+0.2 mV)	$\pm$ (0.1 % of rdg+1.0 mV)				
DCV	2 V	-2.0000 to 2.0000 V	±(0.05 % of rdg+0.5[1.2] mV)	±(0.1 % of rdg+1.0[4.0] mV)				
	6 V	-6.000 to 6.000 V	±(0.05 % of rdg+2 mV)	$\pm$ (0.1 % of rdg+10 mV)				
	20 V	-20.000 to 20.000 V	$\pm$ (0.05 % of rdg+2[3] mV)	±(0.1 % of rdg+10[40] mV)				
	50 V	-50.00 to 50.00 V	±(0.05 % of rdg+0.02 V)	±(0.1 % of rdg+0.10 V)				
	100 V	-100.00 to 100.00 V	±(0.05 % of rdg+0.02 V)	±(0.1 % of rdg+0.10 V)				
Standard signal	0.4-2V	0.3200 to 2.0800 V	±(0.05 % of rdg+0.5[1.2] mV)	±(0.1 % of rdg+1.0[4.0] mV)				
Stariuaru Sigriai	1-5V	0.800 to 5.200 V	±(0.05 % of rdg+2 mV)	$\pm$ (0.1 % of rdg+10 mV)				
	R	0.0 to 1760.0°C	±(0.05 % of rdg+1.0°C)	±(0.1 % of rdg+4.0[6.0]°C)				
TC*4	S	0.0 to 1760.0°C	However, R, S; 0.0 to 800.0°C: ± 1.4°C B; 400.0 to 800.0°C: ± 1.5[3.0]°C	However, R, S; 0.0 to 800.0°C: ± 4.8[7.6]°C B; 400.0 to 800.0°C: ± 7.0[11.0]°C				
(Excluding	В	0.0 to 1820.0°C	Accuracy at less than 400.0°C not guaranteed	Accuracy at less than 400.0°C not guaranteed				
RJC accuracy)	K	-270.0 to 1370.0°C	±(0.05 % of rdg+0.7°C) However, -200.0 to 0.0°C: ±(0.2 % of rdg+0.7°C)	±(0.1 % of rdg+3.5°C) However, -200.0 to 0.0°C: ±(2 % of rdg+3.5°C)				
		-200.0 to 500.0°C	Accuracy at less than -200.0°C not guaranteed	Accuracy at less than -200.0°C not guaranteed				

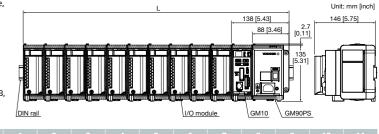
			Measureme	ent accuracy	
Input type	Input type Range		Scan interval: 50 ms or more (Only the Values in [] apply when the scan interval is 50/100/200 ms)	Scan interval: 20 ms or less (Only the Values in [ ] apply when the scan interval is 1/2/5 ms)	
	E	-270.0 to 800.0°C	±(0.05 % of rdg+0.5°C)	±(0.1 % of rdg+2.5°C)	
	J	-200.0 to 1100.0°C	However, -200.0 to 0.0°C: ±(0.2 % of rdg+0.5°C) Accuracy at less than -200.0°C not guaranteed	However, -200.0 to 0.0°C: ±(2 % of rdg+2.5°C) Accuracy at less than -200.0°C not guaranteed	
	cluding	-270.0 to 400.0°C	±(0.05 % of rdg+0.5°C ) However, -200.0 to 0.0°C: ±(0.2 % of rdg+0.5°C ) Accuracy at less than -200.0°C not guaranteed	$\pm$ (0.1 % of rdg+2.5°C) However, -200.0 to 0.0°C: $\pm$ (2 % of rdg+2.5°C) Accuracy at less than -200.0°C not guaranteed	
TC*4		-270.0 to 1300.0°C	±(0.05 % of rdg+0.7°C ) However, -200.0 to 0.0°C: ±(0.5 % of rdg+0.7°C ) Accuracy at less than -200.0°C not guaranteed	$\pm$ (0.1 % of rdg+4.0°C) However, -200.0 to 0.0°C: $\pm$ (3.5 % of rdg+4.0°C) Accuracy at less than -200.0°C not guaranteed	
(Excluding RJC accuracy)		0.0 to 2315.0°C	$\pm$ (0.05 % of rdg+1.0°C ) Less than 1000.0°C: $\pm$ 0.15% of rdg	±(0.1 % of rdg+7.0°C ) However, Less than 1000.0°C: ±(0.8 % of rdg)	
	L	-200.0 to 900.0°C	±(0.05 % of rdg+0.5°C ) Less than 0.0°C: ±(0.25 % of rdg+0.5°C )	±(0.1 % of rdg+2.5°C ) Less than 0.0°C: ±(2 % of rdg+4.0°C )	
	U	-200.0 to 400.0°C	±(0.05 % of rdg+0.5°C ) Less than 0.0°C: ±(0.5 % of rdg+0.5°C )	±(0.1 % of rdg+2.5°C ) Less than 0.0°C: ±(2 % of rdg+2.5°C )	
	WRe3-25	0.0 to 2320.0°C	±(0.05 % of rdg+2.0°C ) Less than 2000.0°C: ± 0.15% of rdg	±(0.1 % of rdg+8.0°C) Less than 200.0°C: 12.0°C Less than 2000.0°C: ±(0.1 % of rdg + 13.0°C)	
RTD*4	Pt100	-200.0 to 850.0°C			
(Measured	1 (100	-150.00 to 150.00°C	±(0.05 % of rdg+0.3°C)	±(0.1 % of rdg+1.5°C)	
current: 1 mA)	IPt100	-200.0 to 550.0°C			
	<b>J</b>	-150.00 to 150.00°C			
DI	Level		Threshold level (Vth=2.4 V) accuracy $\pm$ 0.1 V		
5.	Contact		100 k $\Omega$ or less: 1 (ON), 10 k $\Omega$ or more: 0 (OFF)		

<sup>\*1</sup> Reference operating conditions: 23  $\pm$  2°C, 55  $\pm$  10% RH, supply voltage 90–132, 180–264 VAC, supply frequency within 50/60 Hz  $\pm$  1%, warmup 30 minutes or more, no vibrations or other hindrances to performance. Please inquire for modules with increased guaranteed accuracy specifications. rdg: reading value

- \*2 10 channel mode with scan interval set to 500 ms or higher, or 2 channel mode
- \*3 10 channel mode with scan interval set to 100 ms or 200 ms

  \*4 For the measuring ranges and accuracy below, see the general specification (GS 04L53B00-01EN).

(GS 04L35800/1EN).
TC: KpvsAu7Fe, PLATINEL II, PR20-40, NiNiMo, W/WRe26, N(AWG14), XK GOST
RTD: Cu10 GE, Cu10 L&N, Cu10 WEED, Cu10 BAILEY, Cu10, Cu25, Cu53, Cu100, J263B, Ni100 (SAMA), Ni100 (DIN), Ni120, Pt25, Pt50, Pt200 WEED, Cu10 GOST, Cu50 GOST, Cu100 GOST, Pt46 GOST, Pt100 GOST



Connected modules	1	2	3	4	5	6	7	8	9	10	11
L (mm)	138 [5.43]	188 [7.40]	238 [9.37]	288 [11.34]	338 [13.31]		438 [17.24]	488 [19.21]	538 [21.18]	588 [23.15]	638 [25.12]

#### **MODEL AND SUFFIX CODES**

#### MODEL and SUFFIX Code (GM10)

				Optional code	
GM10					Data Acquisition Module for SMARTDAC+ G
Tuna	-1				Standard (Max. measurement channels: 100 ch)
Туре	-2				Large memory (Max. measurement channels: 500 ch)
Area		Е			General (temp. unit: Cel, Deg F)*7
_			0		Always 0
				/AH	Aerospace heat treatment
				/AS	Advanced security function*4
				/BT	Multi-batch function*5
				/C3	RS-422/485
				/C8	Bluetooth
				/E1	EtherNet/IP communication (PLC communication protocol)
Optional fe	eature	S		/E2	WT communication*1
				/E3	OPC-UA sever
				/E4	SLMP communication (Mitsubishi PLC)
				/MT	Mathematical function (with report function)*
				/MC	Communication channel function
				/LG	Log scale
				/PG	Program control function*6

#### MODEL and SUFFIX Code (GM90PS)

GM90PS						Power Supply Module for SMARTDAC+ GM
Туре	-1					Always -1
Area		N				General
Cupply voltage						100 to 240 V AC
Supply voltage 2		2			12-28 VDC*	
				D		Power inlet with UL/CSA cable
				F		Power inlet with VDE cable
				Н		Power inlet with GB cable
Power supp	ply co	nnecti	on	N		Power inlet with NBR cable
				Q		Power inlet with BS cable
				R		Power inlet with AS cable
				W		Screw terminal (without power cable)
-						Always 0

<sup>\*</sup> Only W (Screw terminal (M4)) is available for the power supply connection.

#### MODEL and SUFFIX Code (GM90MB)

Model	S	uffix cod	е	Descripiton
GM90MB				Module Base for SMARTDAC+ GM
-	-01			Always -01
Area		N		General
-			0	Always 0

- \*2 Optional code /MT (MATH) required if using the GX90XD's or GX90WD's pulse input.
- 43 Optional code /MT (MATH) required if using the GX90XP's pulse integration.
   44 When the Advanced Security function is ON the scan interval is 100 ms or more, and the Dual Interval function and PID modules are unavailable.
   45 When the Multibatch function is ON the scan interval is 500 ms or more, and the Dual Interval function is unavailable.
- \*6 Using the Program Control function requires the PID control module.
- \*7 The Display language is selectable from English, German, French, Italian, Russian, Korean, Simplified Chinese, Traditional Chinese, Japanese.

#### MODEL and SUFFIX Code (GX90XA)

						•
Model						Description
GX90XA						Analog Input Module
	-4					4 channels (-H0 type only)
Number of channels	-6					6 channels (-R1 type only)
CHAINTEIS	-10					10 channels (-C1, -L1, -U2, -T1, -V1)
		-C1				Current, scanner type (isolated between channels)
		-L1				DCV/TC/DI, low withstand voltage scanner type (isolated between channels)
		-U2				Universal, Solid state relay scanner type (3-wire RTD b-terminal common)
Туре		-T1				DCV/TC/DI, Electromagnetic relay scanner type (isolated between channels)
		-H0				High speed universal, individual A/D type (isolated between channels)
		-R1				4-wire RTD/resistance, scanner type (isolated between channels)
		-V1				DCV/TC/DI, high withstand voltage scanner type (isolated between channels)
_			N			Always N
Terminal fo	orm			-3		Screw terminal (M3)
remillal I	ווווכ			-C		Clamp terminal*
Area					N	General

#### MODEL and SUFFIX Code (GX90XD)

GX90XD						Digital Input Module
Number of channels	-16					16 channels
Туре		-11				Open collector/Non-voltage, contact (shared common), Rated 5 VDC
_			N			Always N
Terminal form				-3		Screw terminal (M3)
Terminal form				-C		Clamp terminal
Area					N	General

#### MODEL and SUFFIX Code (GX90YD)

Model		Sui	ffix co	de		Description
GX90YD						Digital Output Module
Number of channels	-06					6 channels
Type		-11				Relay, SPDT(NO-C-NC)
_			N			Always N
Terminal form -3						Screw terminal (M3)
Area					N	General

#### MODEL and SUFFIX Code (GX90WD)

						Description
GX90WD						Digital Input/Output Module
Number of channels	-0806					8 channel DIs, 6 channel DOs
Туре		-01				Input: Open collector/non-voltage contact (shared common), rated 5 VDC Output: Relay, SPDT (NO-C-NC)
-			N			Always N
Terminal form -3						Screw terminal (M3)
Area					N	General

#### MODEL and SUFFIX Code (GX90XP)

				•		
GX90XP						Pulse Input Module
Number of channels	-10					10 channels
Туре		-11				DC voltage/open collector/non-voltage contact (shared common), rated 5 VDC
_			N			Always N
Terminal form						Screw terminal (M3)
-C			-C		Clamp terminal	
Area					N	General

#### MODEL and SUFFIX Code (GX90EX)

Model		Suffix	code		Descripiton
GX90EX					I/O Expansion Module
Port	-02				2 ports
Туре		-TP1			Twisted pair cable
_			N		Always N
Area				-N	General

#### MODEL and SUFFIX Code (GX90YA)

Model		Sui	ffix co	ode		Descripiton
GX90YA						Analog Output Module
Number of channels	-04					4channels
Туре		-C1				Current output (isolated between channels)
-			N			Always N
Tauraia al fau				-3		Screw terminal (M3)
Terminal form -C						Clamp terminal
Area					N	General

#### MODEL and SUFFIX Code (GX90UT)

Model	Suffix code			Description		
GX90UT						PID Control Module
Number of loops	-02					2 loops
Function		-11				8 DIs, 8 DOs
- N				Always N		
Terminal form -3		-3		Screw terminals (M3)		
Area				N	General	

#### MODEL and SUFFIX Code (GX90NW)

Model	Suffix code			Description		
GX90NW						Network Module
Port	-02					2 ports
Туре		-PN				PROFINET
_			N			Always N
Terminal form -R		-R		RJ-45 Connector		
Area		N	General			

#### **Standard Accessories**

Model	Product	Qty
GM10	SD memory card (1GB)	1
GM90PS	Connector cover	1
	Power cable (depends on the suffix code of the power supply connection)	1
	Interconnect screw (M3)	4
GM90MB	Interconnect screw (M3)	4

#### **Optional Accessories (Sold Separately)**

Product	Part Number/ Model
SD memory card (1GB)	773001
Shunt resistor for screw terminal (M3) (250 $\Omega \pm$ 0.1%)	415940
Shunt resistor for screw terminal (M3) (100 $\Omega \pm$ 0.1%)	415941
Shunt resistor for screw terminal (M3) (10 $\Omega$ $\pm$ 0.1%)	415942
Shunt resistor for clamp terminal (250 $\Omega \pm$ 0.1%)	438920
Shunt resistor for clamp terminal (100 $\Omega \pm$ 0.1%)	438921
Shunt resistor for clamp terminal (10 $\Omega \pm$ 0.1%)	438922
Dummy cover	B8740CZ
Validation Documents (For /AS option)	773230

#### **Application Software (Sold Separately)**

Model		OS
GA10	Data Logging Software	Windows 8.1/10/11 Windows Server 2012/2016/2019

Calibration certificate (sold separately)
 A calibration certificate for specific analog input modules.

#### Test certificate (QIC, sold separately)

A QIC for specific data acquisition modules, power supply modules, module bases, or I/O modules.

#### User's Manual

Product user's manuals can be downloaded or viewed at the following URL. URL: www.smartdacplus.com/manual/en/

#### **Equipment/Quality Predictive Detection tool**

(This tool is required to create Predictive detection model and Profile waveform.

Cloud Equipment/Qualtiy Predictive Detection tool

You need to apply online before purchasing the cloud version of Equipment/Quality Predictive Detection tool. http://www.smartdacplus.com/)

#### Cloud version

CLIO		(Validity period : 12 months)
Optional /AU		Predictive Detection model download license for SMARTDAC+ 1 unit
Model	Suffix code	Description
CE10L		Cloud Predictive Detection model download license
	-01	SMARTDAC+ 1 unit
Number of	-03	SMARTDAC+ 3 units
units using	-05	SMARTDAC+ 5 units
the predictive	-10	SMARTDAC+ 10 units
detection model	-20	SMARTDAC+ 20 units
model	-50	SMARTDAC+ 50 units
	-A0	SMARTDAC+ 100 units

#### Offline version

Model	Suffix code	
OE10		Offline Equipment/Quality Predictive Detection tool with Predictive Detection model download license for 1 unit

Model	Suffix code	Description
OE10L		Offline Predictive Detection model download license
	-01	SMARTDAC+ 1 unit
No combana of	-03	SMARTDAC+ 3 units
Number of units using the predictive detection model	-05	SMARTDAC+ 5 units
	-10	SMARTDAC+ 10 units
	-20	SMARTDAC+ 20 units
	-50	SMARTDAC+ 50 units
	-A0	SMARTDAC+ 100 units

## Configuration example (with a supply voltage of 100-240 VAC, power inlet, universal input, and clamp terminal)

#### Single-unit configuration example

#### 30 ch (analog input)

GM10-1E0	x 1
GM90PS-1N1D0	x 1
GX90XA-10-U2N-CN	x 3
GM90MB-01N0	x 4

GM90PS-1N1D0

GM90MB-01N0

GM10-1E0

#### **100**ch (analog input)

Χ	1
Х	1
Х	10
Х	11
	X



#### **Multi-unit configuration example**

#### 120ch (analog input)

GM10-2E0	Х	1
GM90PS-1N1D0	Х	2
GX90XA-10-U2N-CN	Х	12
GX90EX-02-TP1N-N	Χ	2
GM90MB-01N0	Х	15



#### **300**ch (analog input)

**60**ch (analog input)

GX90XA-10-U2N-CN x 6

x 1

x 1

GM10-2E0	x 1
GM90PS-1N1D0	x 5
GX90XA-10-U2N-CN	x 30
GX90EX-02-TP1N-N	x 5
GM90MB-01N0	x 36



#### 420ch (analog input)

GM10-2E0	Χ	1
GM90PS-1N1D0	Х	7
GX90XA-10-U2N-CN	Х	42
GX90EX-02-TP1N-N	Х	7
GM90MB-01N0	x	50



## Paperless recorder GX/GP

With the touch panel, reliability meets user empowerment in an expanding range of applications.



#### **Data Logging Software GA10 (sold separately)**

#### Centrally acquire data from multiple devices on a PC

GA10 is a PC based software package that acquires real time data from SMARTDAC+ data acquisition systems and other devices connected to a network. Connected PCs can monitor real time and historical data, which can be stored on a PC harddrive or centrally on a network drive.



Max. connectable units: 100 Max. recording tags (channels): 10,000

Scan interval: 100 ms (channels)

#### Compatible with other models in addition to the GM!





GP10/GP20 WT series (power analyzers)

Supports many other models. For details, see the GA10 catalog.

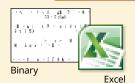
#### Aggregate data for monitoring!



Easy to read screen layouts provide operator friendly real time monitoring.

- Group channels any way you like
- Play back data up to recording start, even during measurement
- Instantly recognize alarms (in red)

#### Save the data all together!

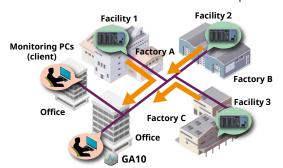


Data is stored in a binary tamper proof format preventing unauthorized access. Data can also be exported to excel format for data manipulation and analysis.

#### **Application example**

#### Data monitoring in manufacturing sites

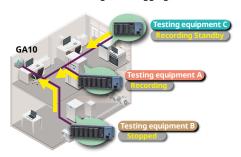
Monitor factory data from the office. You can also add clients and share data across multiple PCs.



Effect: No more moving around large factories to do work!

#### Recording data from multiple equipments

Saves testing/manufacturing equipment data on a PC. In addition to simultaneous acquisition, you can acquire data from different equipment at different timing (multilogging).



Effect: Manage all data on the PC, one set of equipment at a time!

#### **WEB** site

http://www.smartdacplus.com/



#### **User Registration Request**

Please register to the following Partner Portal Member Site. You can use various services such as confirmation of purchased product information, download of related materials and software.

Customer Portal Member Site >>> https://myportal.yokogawa.com/



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Before operating the product, read the instruction manual thoroughly for proper and safe operation.

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A7-S-2F Printed in Japan, 408(AZ) [Ed:09/d]



